

Phase Noise in Oscillators

Ali Hajimiri

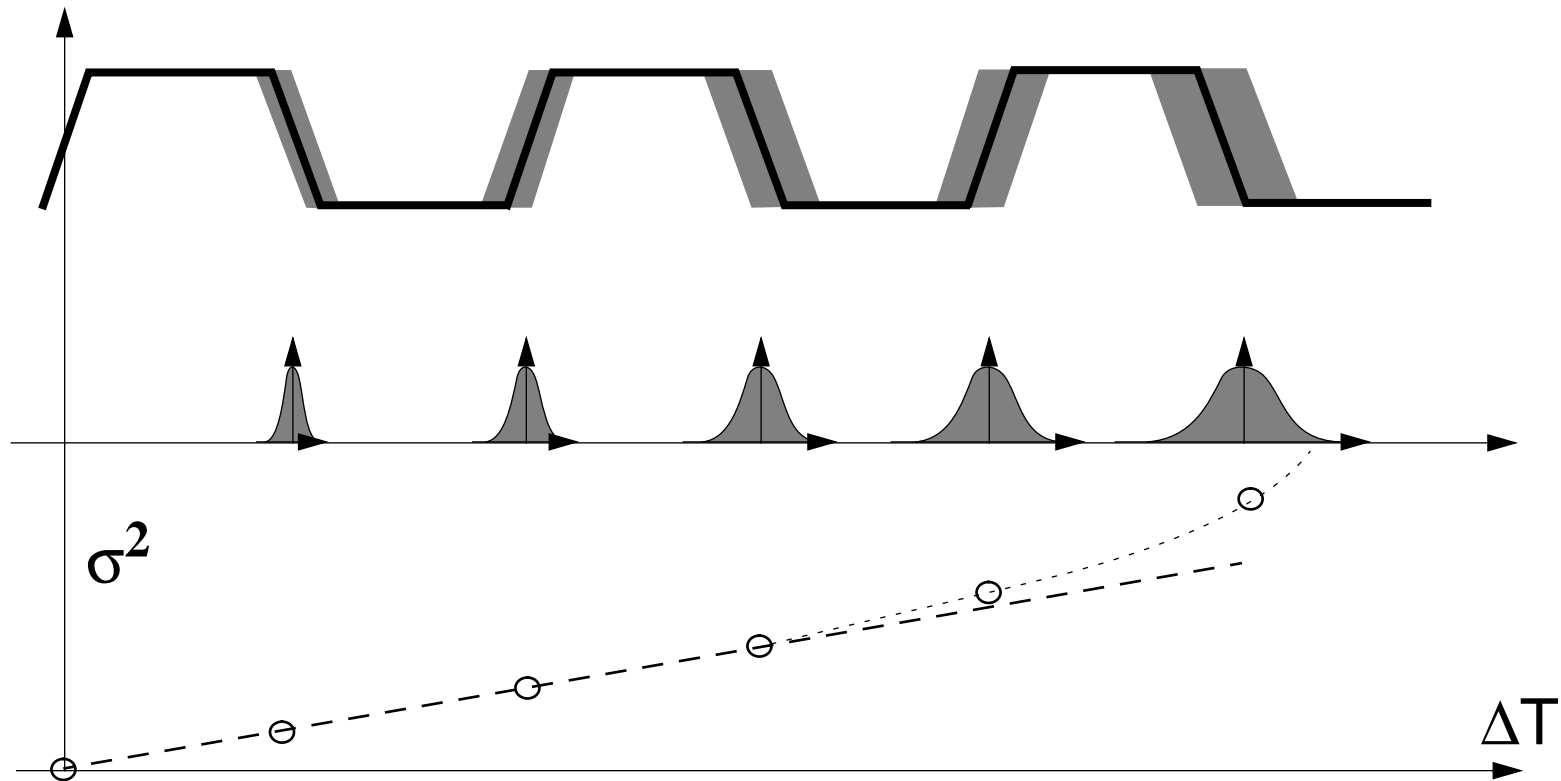
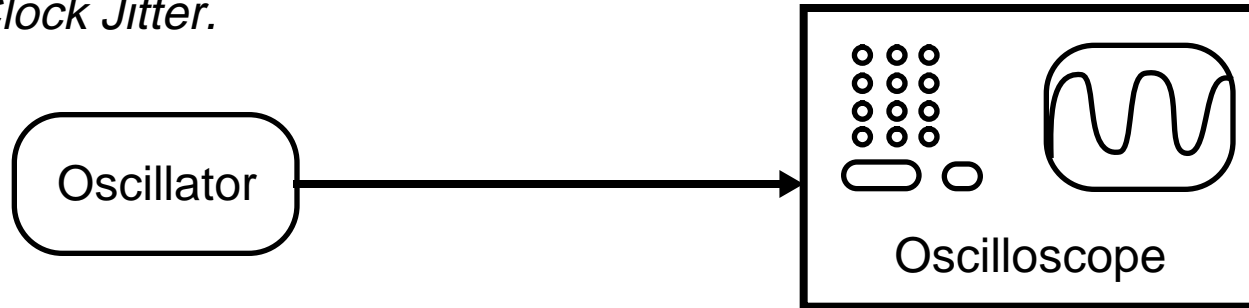
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Outline

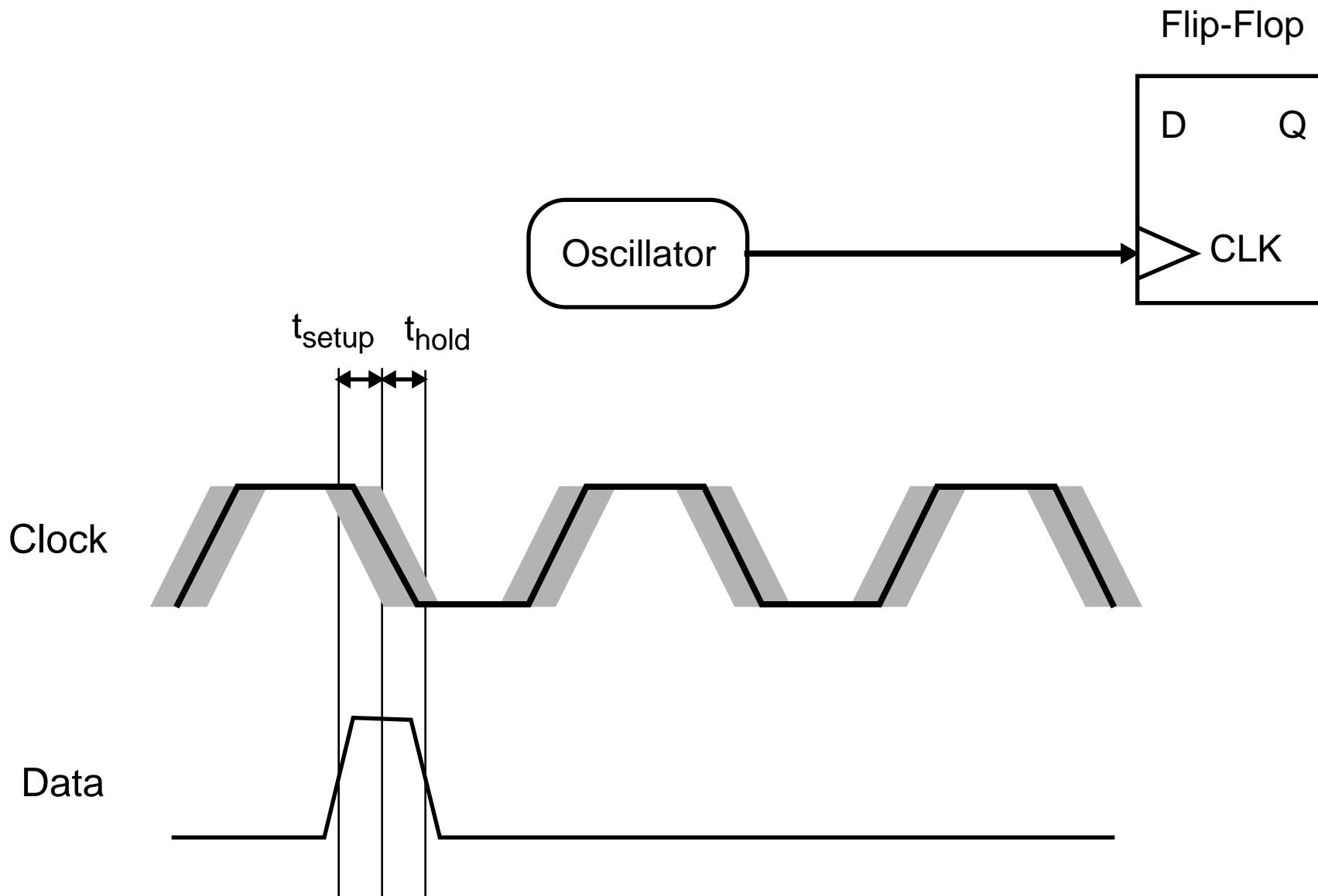
- ***Introduction and Definitions***
- Time-Variant Phase Noise Model
 - Upconversion of $1/f$ Noise
 - Cyclostationary Noise Sources
 - Substrate and Supply Noise
- Measurement Results
- Conclusion

Frequency Instability: Time Domain

Known As Clock Jitter.

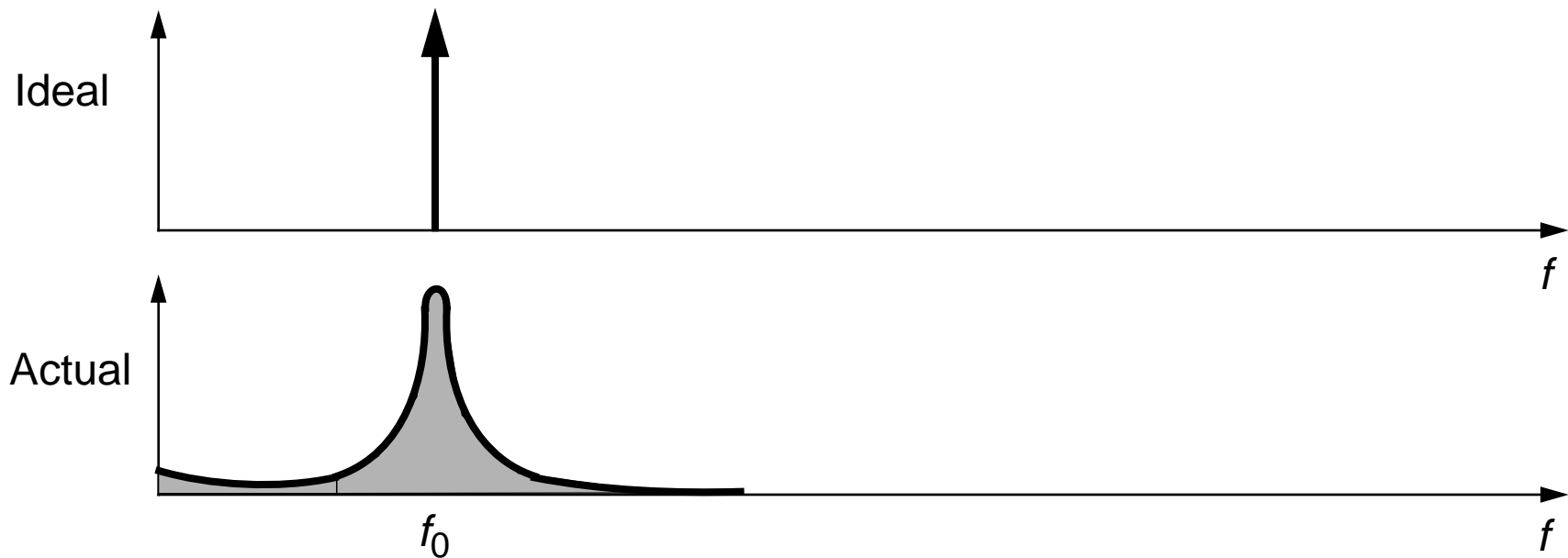
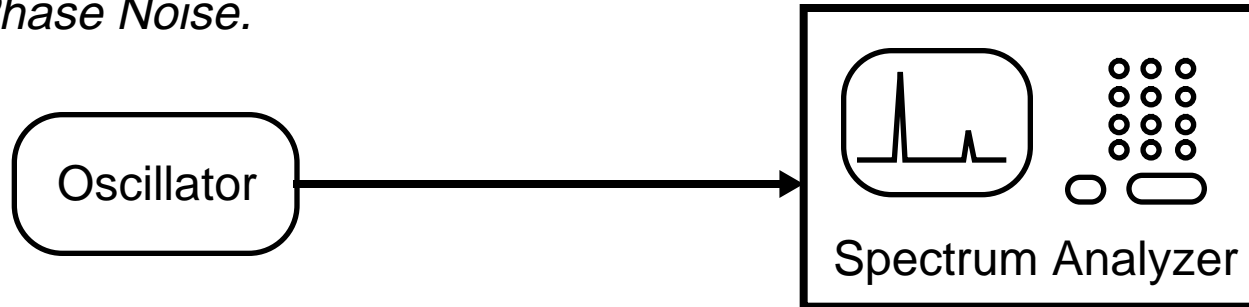


Timing Jitter in Digital Applications

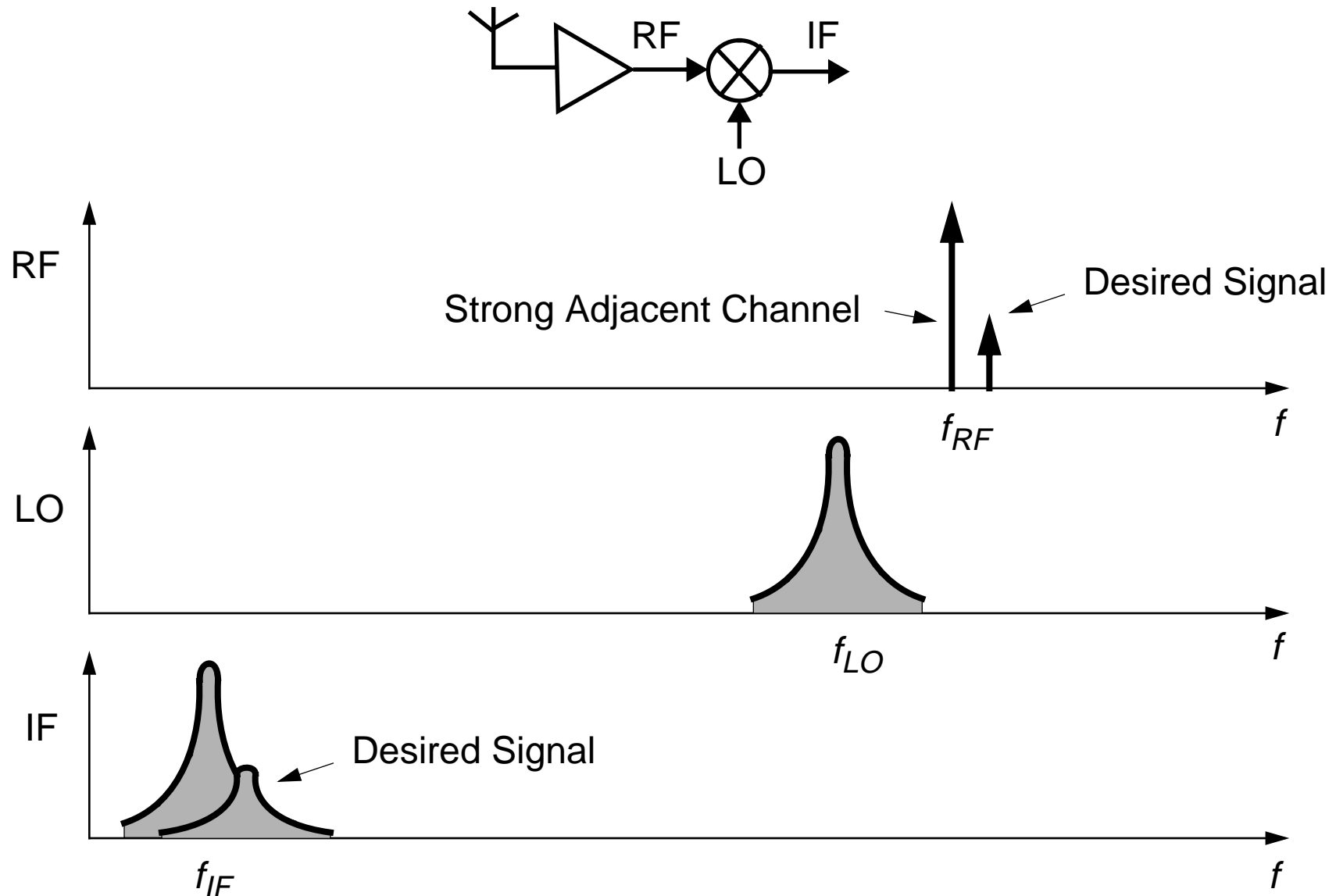


Frequency Instability: Frequency Domain

Known As Phase Noise.

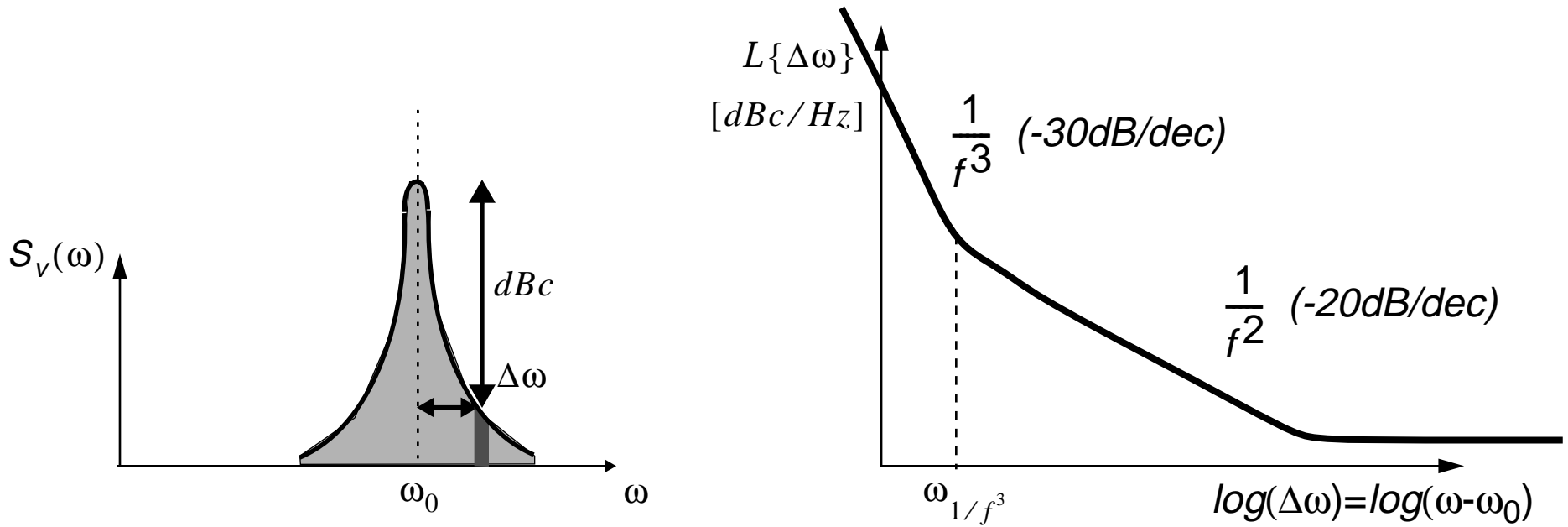


Phase Noise in RF Applications



The desired signal is buried under the phase noise of an adjacent strong channel.

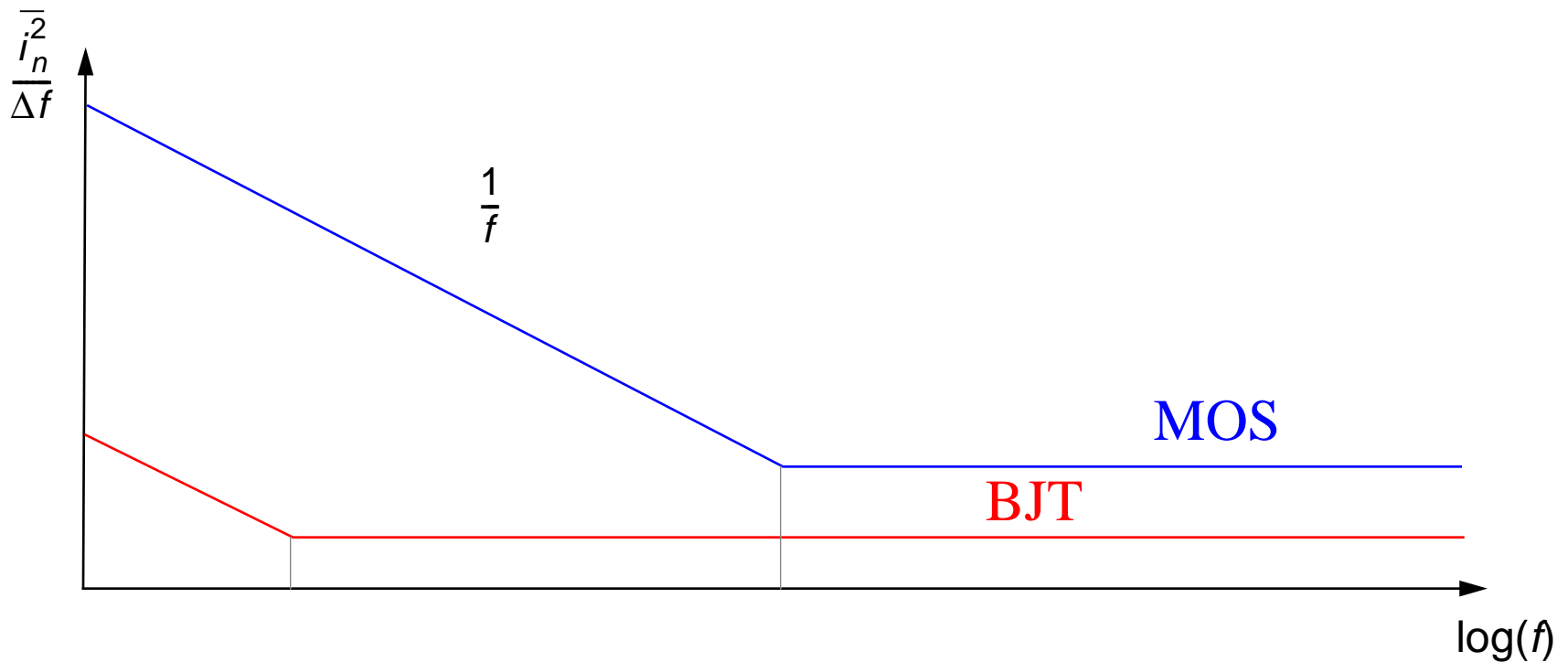
Units of Phase Noise



Measured in dB below carrier per unit bandwidth.

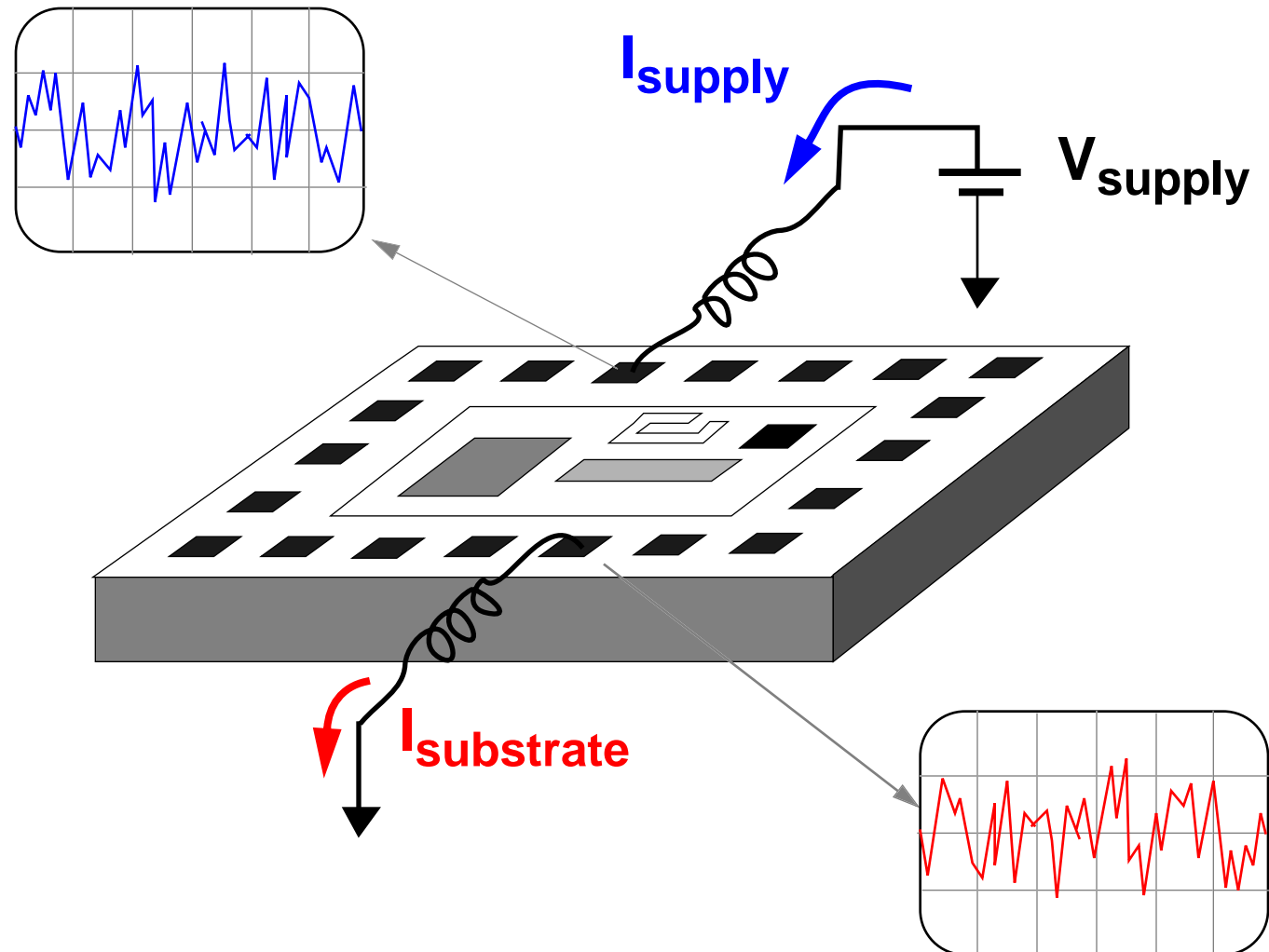
Thermal and 1/f Noise

Internal noise sources set a fundamental limit for phase noise.



Low frequency noise can be an important contributor to the system noise.

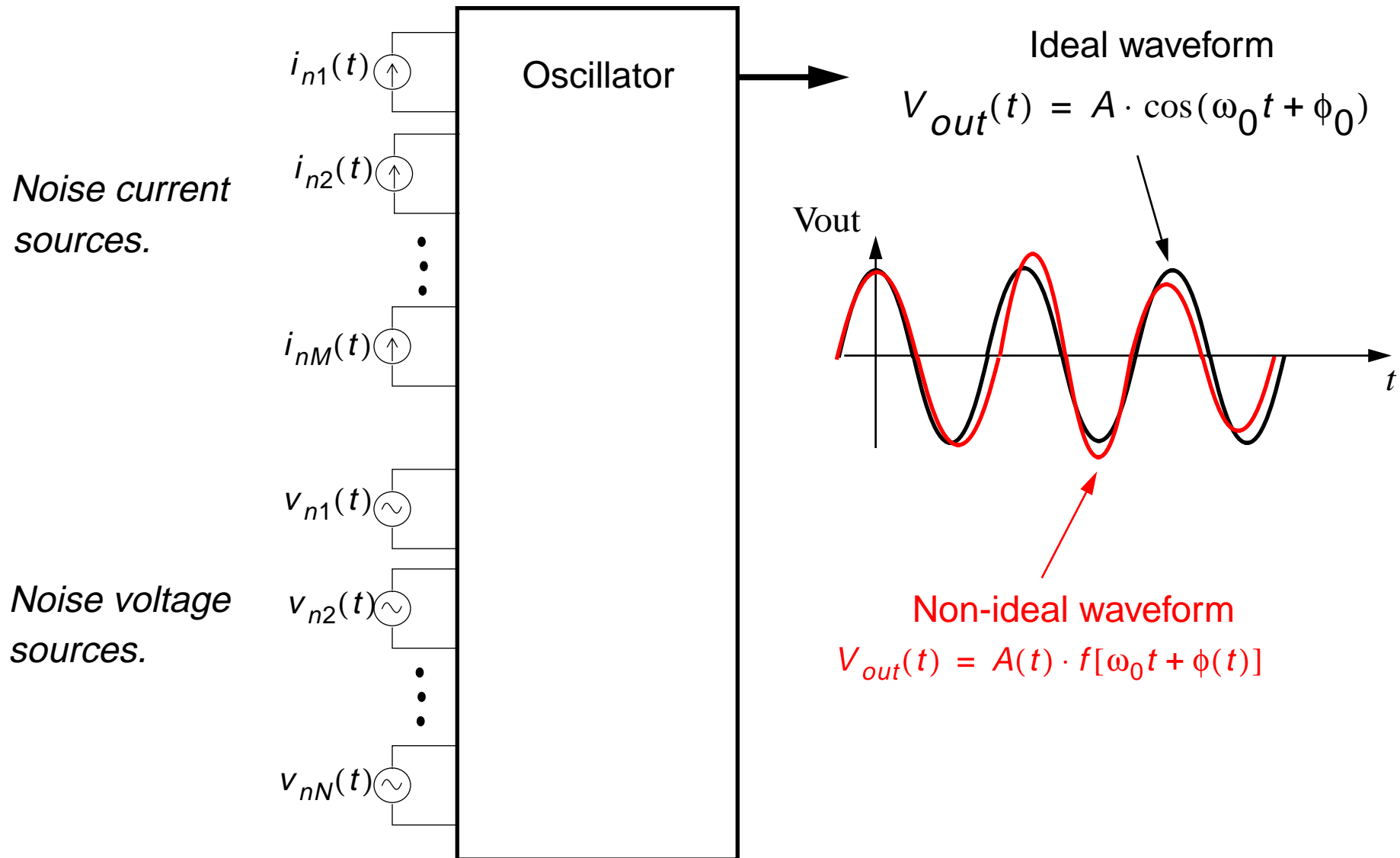
Substrate and Supply Noise



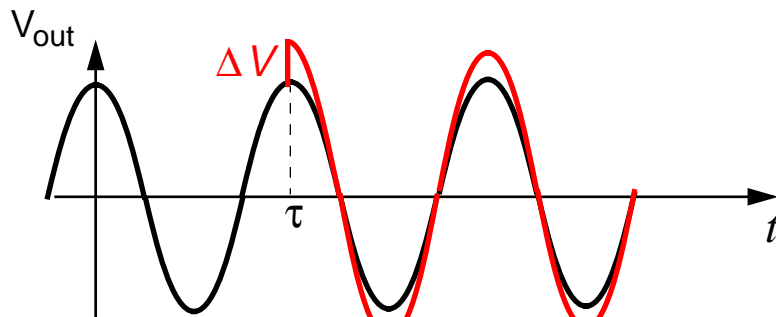
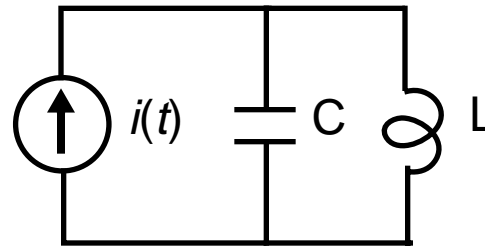
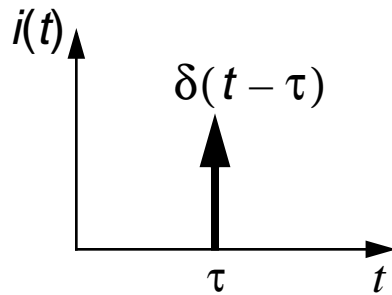
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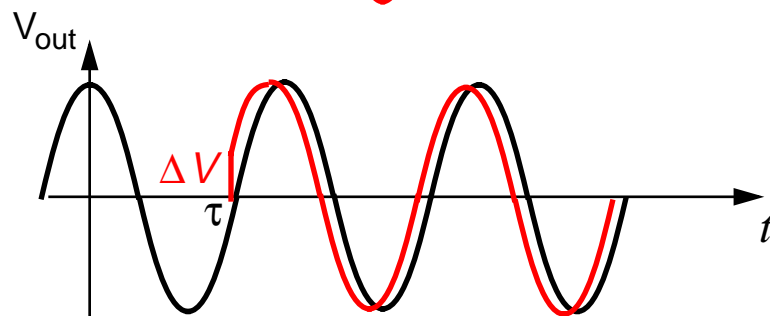
Oscillator with Input Noise Sources



Oscillators Are Time-Variant Systems



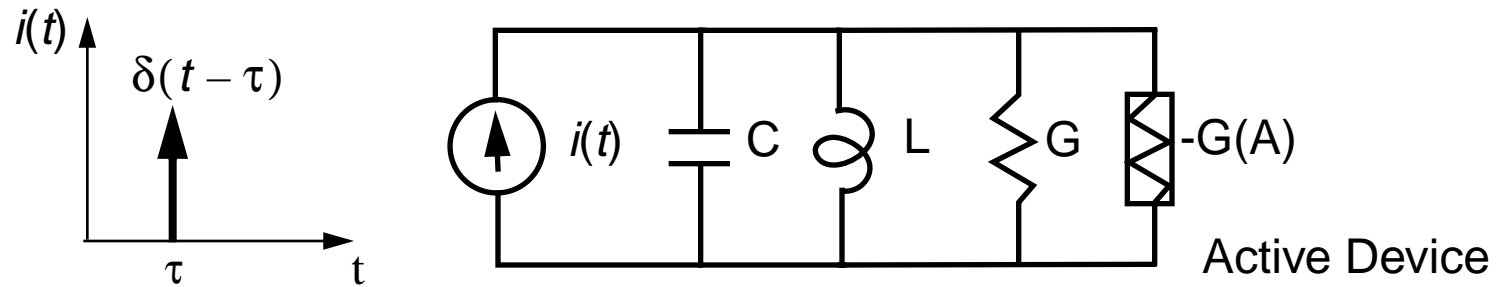
Impulse injected at the peak of amplitude.



Impulse injected at zero crossing.

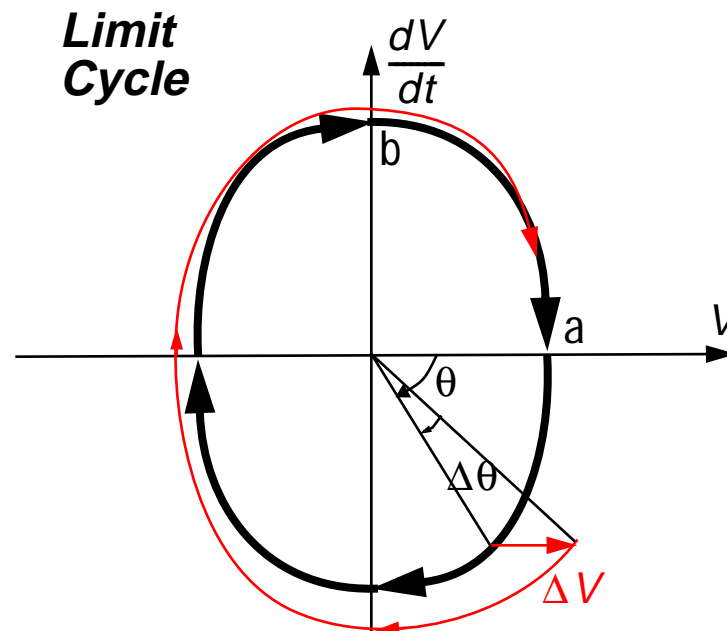
Even for an ideal LC oscillator, the phase response is *Time Variant*.

Amplitude Restoring Mechanism

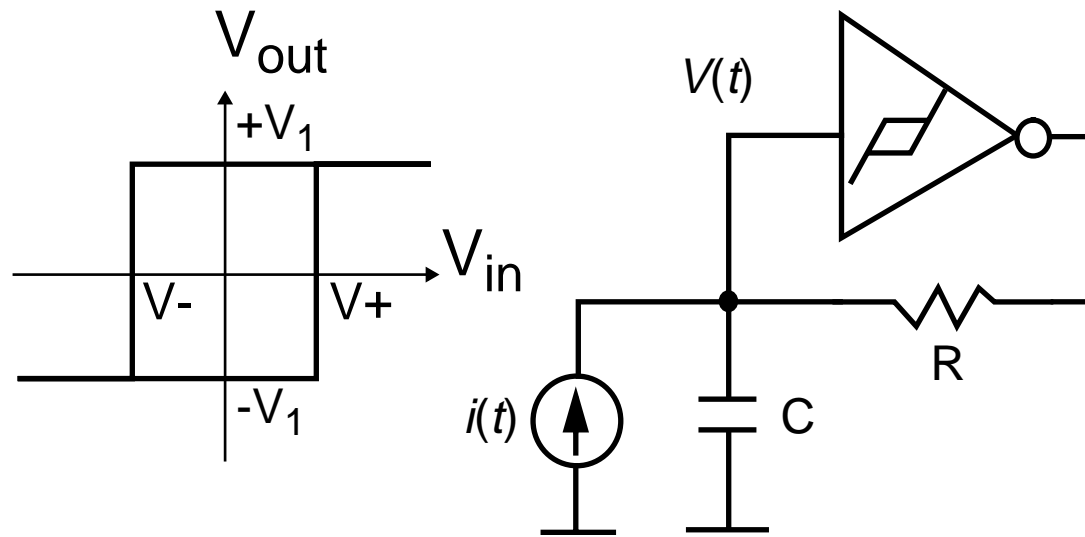


Once Introduced, phase error persists indefinitely.

Non-linearity quenches amplitude changes over time.



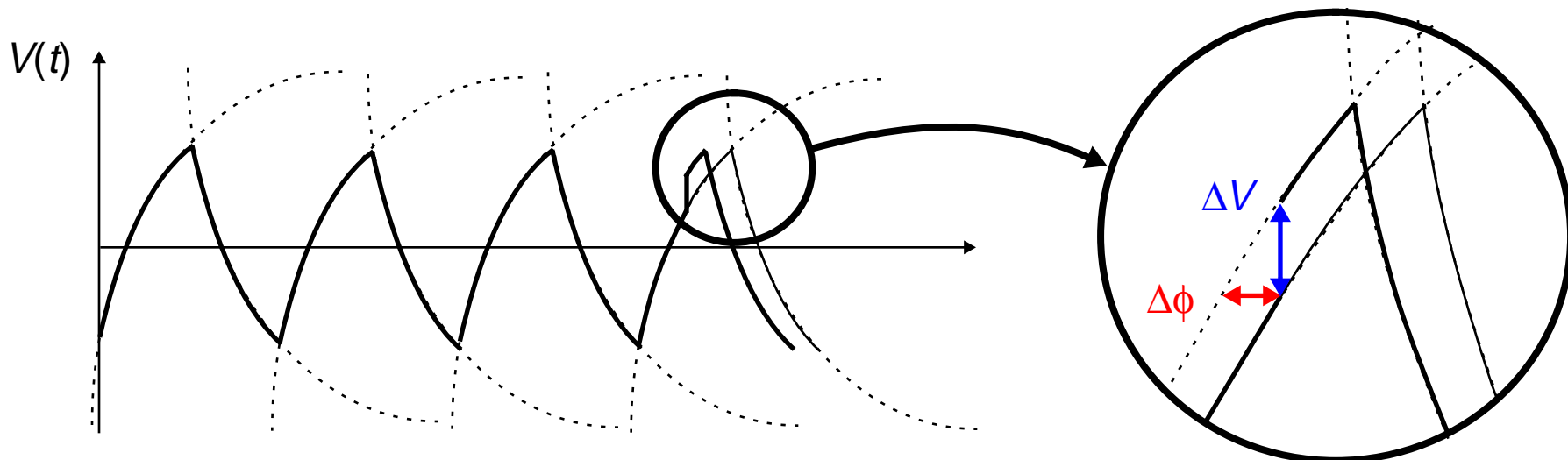
Impulse Response of a Relaxation Oscillator



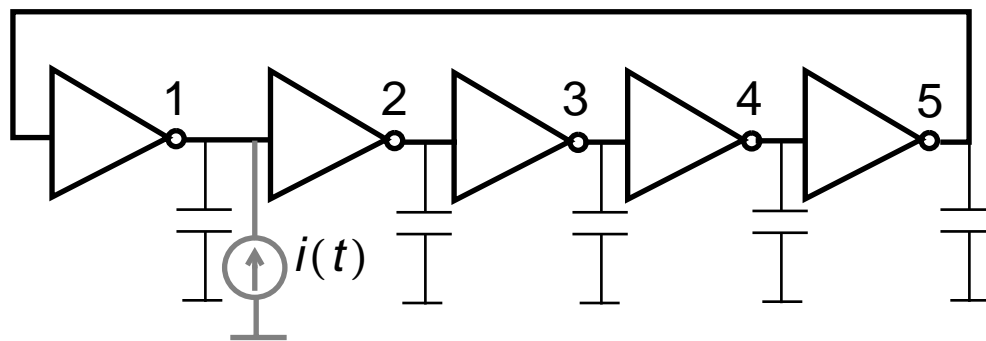
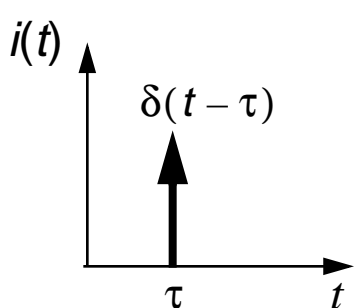
$$\Delta V = \frac{\Delta q}{C_{node}}$$

$$\Delta \phi = \Gamma(\omega_0 t) \frac{\Delta V}{V_{swing}} = \Gamma(\omega_0 t) \frac{\Delta q}{q_{swing}}$$

$$\Delta q \ll q_{swing}$$



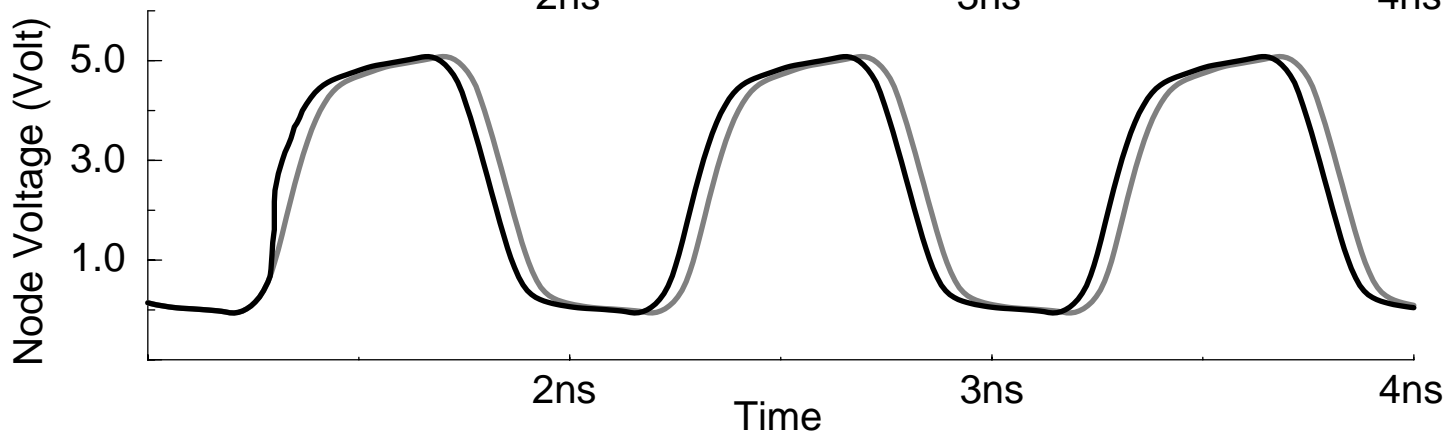
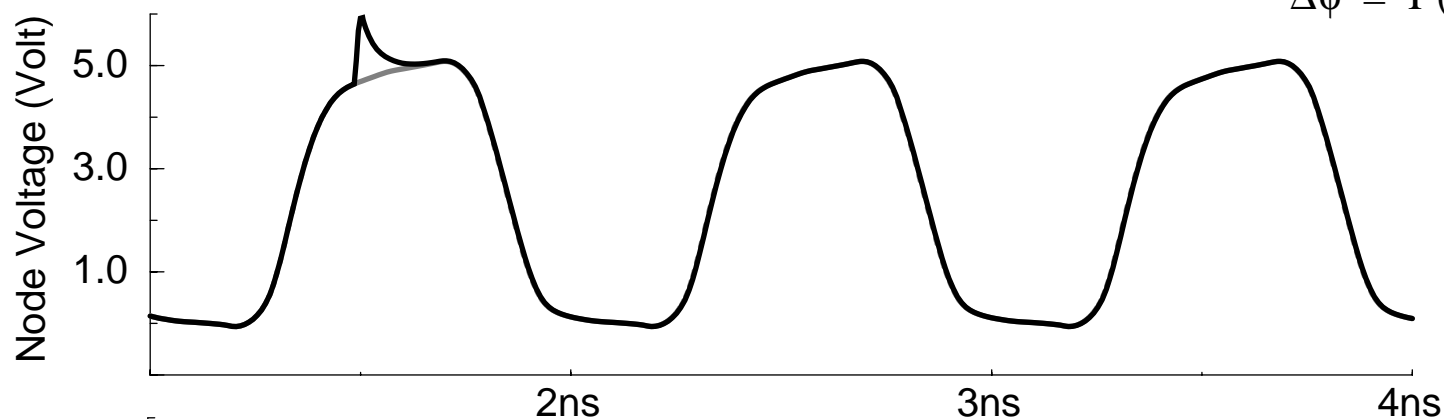
Impulse Response of a Ring Oscillator



$$\Delta V = \frac{\Delta q}{C_{node}}$$

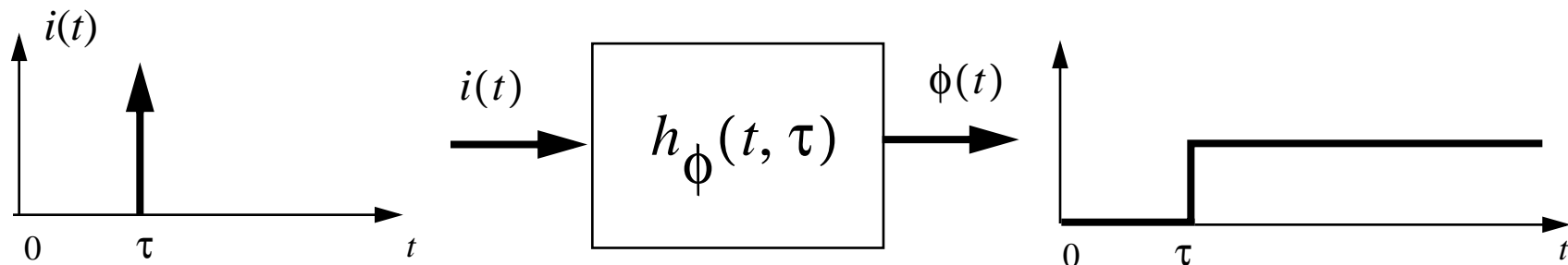
$$\Delta \phi = \Gamma(\omega_0 t) \frac{\Delta V}{V_{swing}} = \Gamma(\omega_0 t) \frac{\Delta q}{q_{swing}}$$

$$\Delta q \ll q_{swing}$$



Phase Impulse Response

The phase impulse response of an arbitrary oscillator is a time varying step.



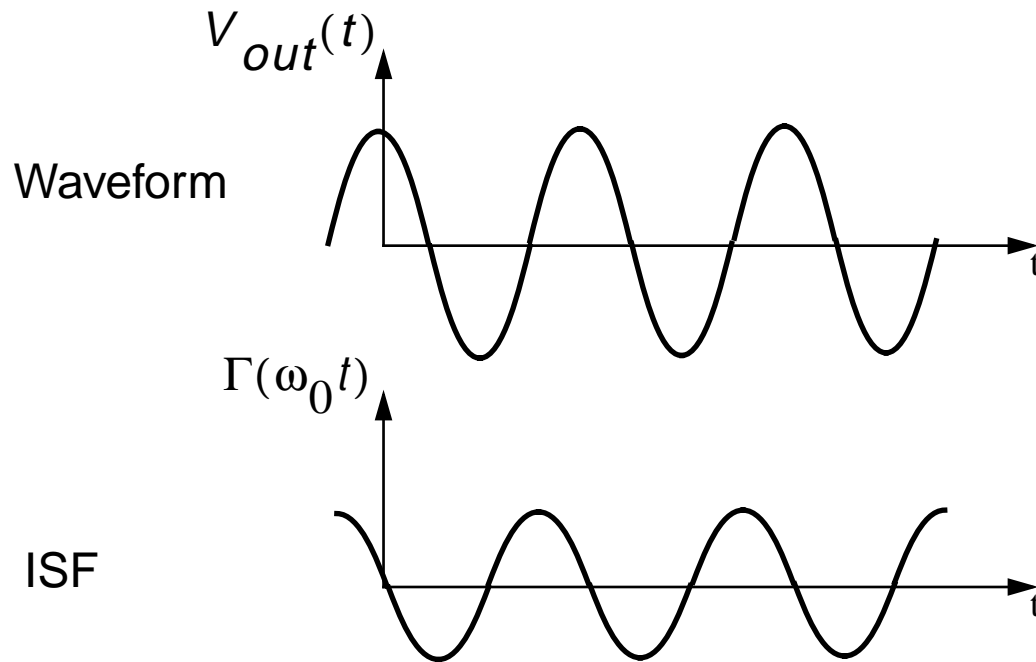
The unit impulse response is:

$$h_{\phi}(t, \tau) = \frac{\Gamma(\omega_o \tau)}{q_{max}} u(t - \tau)$$

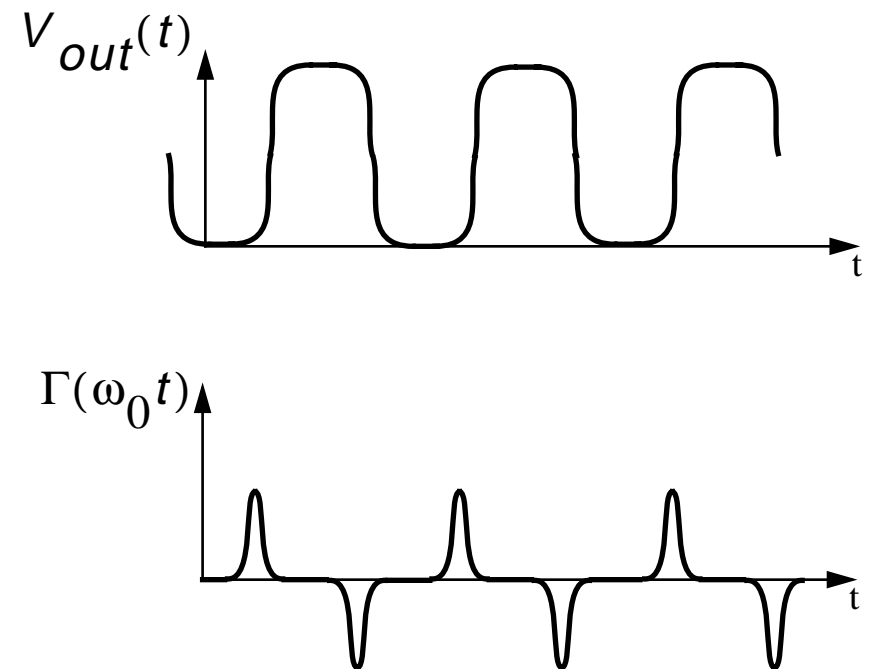
$\Gamma(x)$ is a dimensionless function periodic in 2π , describing how much phase change results from applying an impulse at time: $t = T \frac{x}{2\pi}$

Impulse Sensitivity Function (ISF)

LC Oscillator

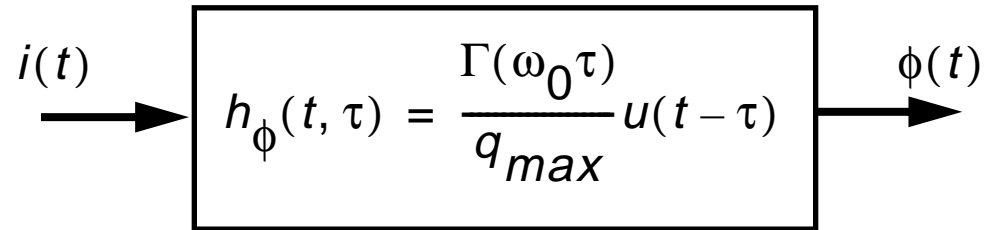


Ring Oscillator



The ISF quantifies the sensitivity of every point in the waveform to perturbations.

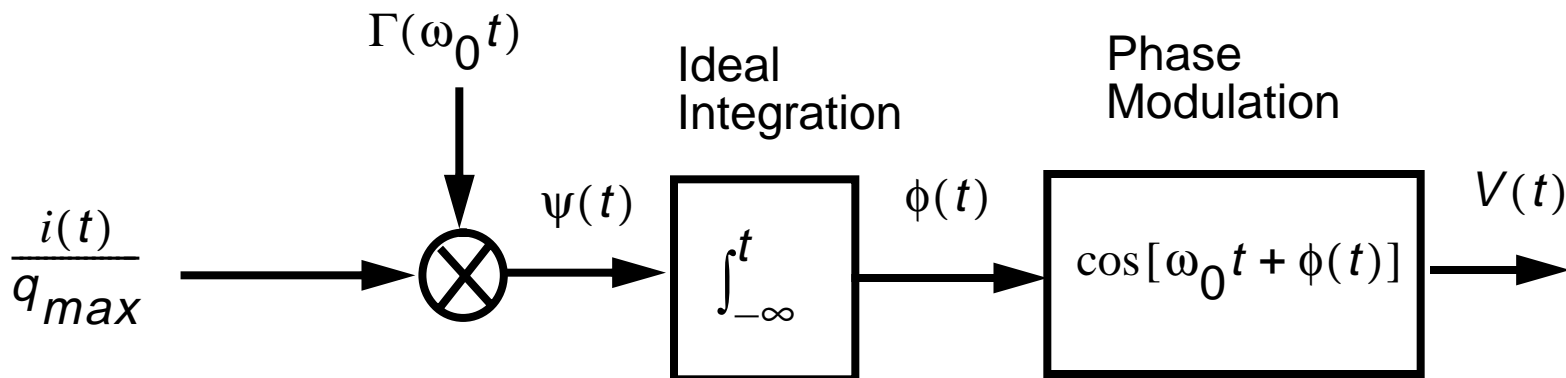
Phase Response to an Arbitrary Source



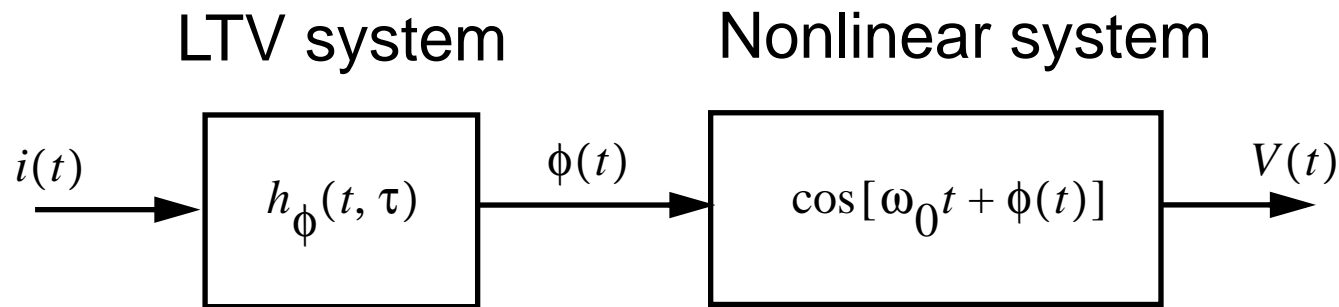
Superposition Integral:

$$\phi(t) = \int_{-\infty}^{\infty} h_{\phi}(t, \tau) i(\tau) d\tau = \frac{1}{q_{max}} \int_{-\infty}^t \Gamma(\omega_0 \tau) i(\tau) d\tau$$

Equivalent representation:



Phase Noise Due to White Noise



For a white input noise current with the spectral density of $\overline{i_n^2} / \Delta f$

The phase noise sideband power below carrier at an offset of $\Delta\omega$ is:

$$L\{\Delta\omega\} = \frac{\Gamma_{rms}^2}{q_{max}^2} \cdot \frac{\overline{i_n^2} / \Delta f}{2\Delta\omega^2}$$

Γ_{rms} is the rms value of the ISF.

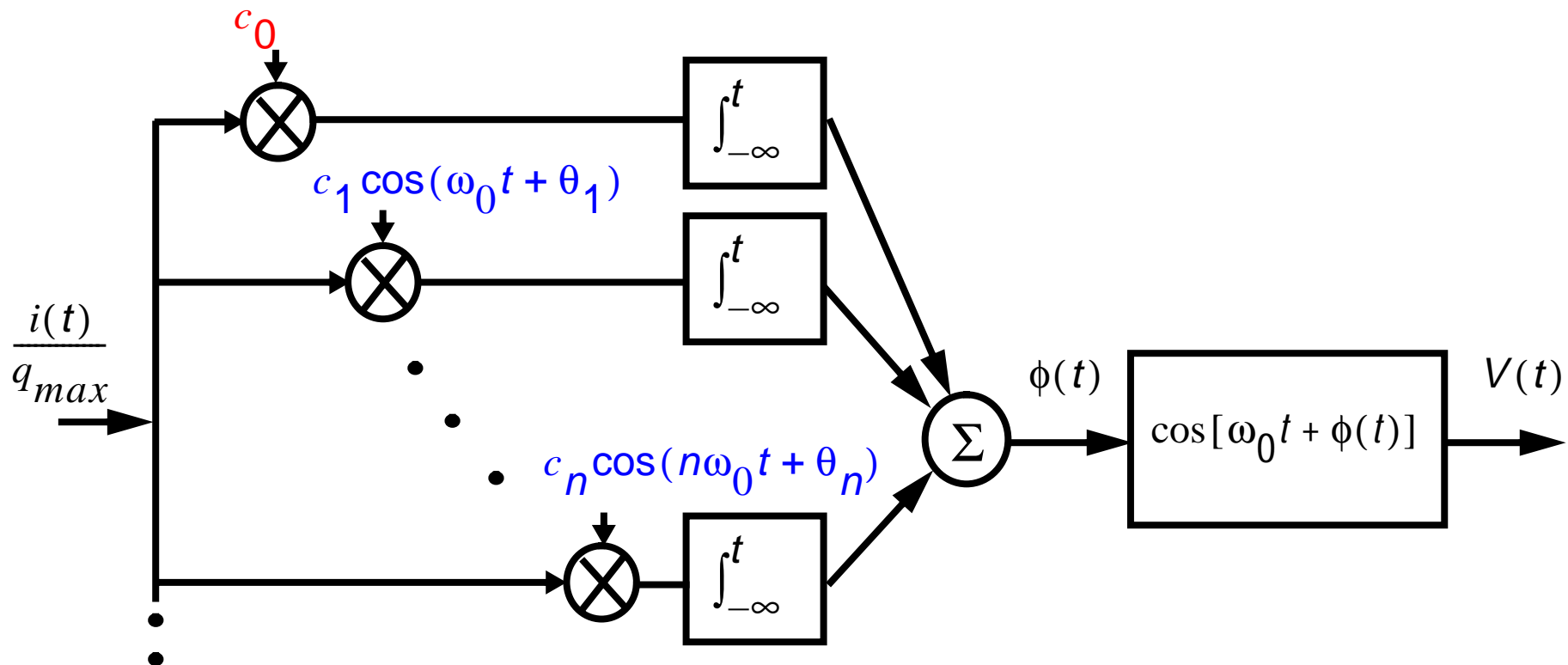
ISF Decomposition

ISF is a periodic function:

$$\Gamma(\omega_0 t) = c_0 + \sum_{n=1}^{\infty} c_n \cos(n\omega_0 t + \theta_n)$$

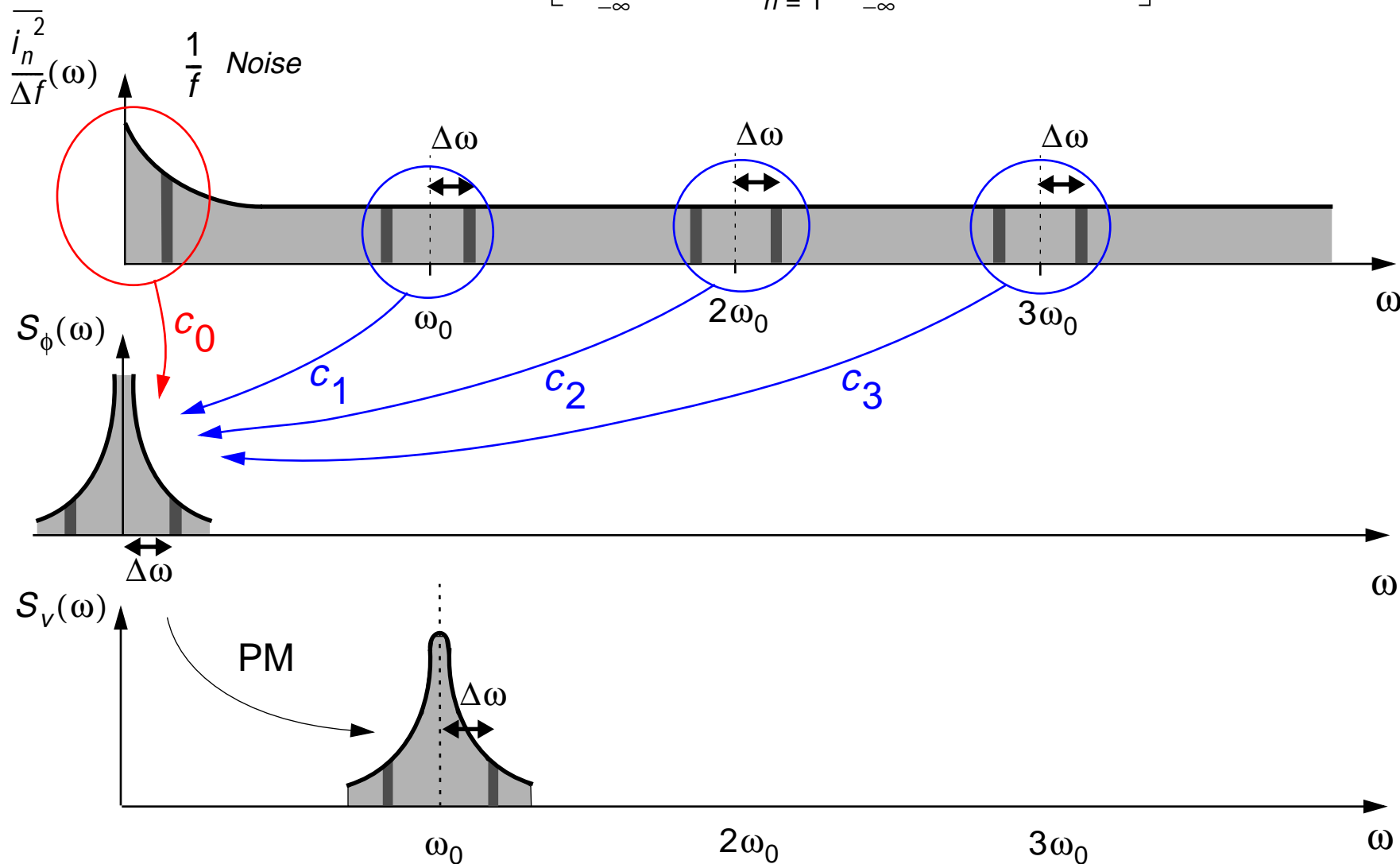
Phase can be written as:

$$\phi(t) = \frac{1}{q_{max}} \left[c_0 \int_{-\infty}^t i(\tau) d\tau + \sum_{n=1}^{\infty} c_n \int_{-\infty}^t i(\tau) \cos(n\omega_0 \tau) d\tau \right]$$

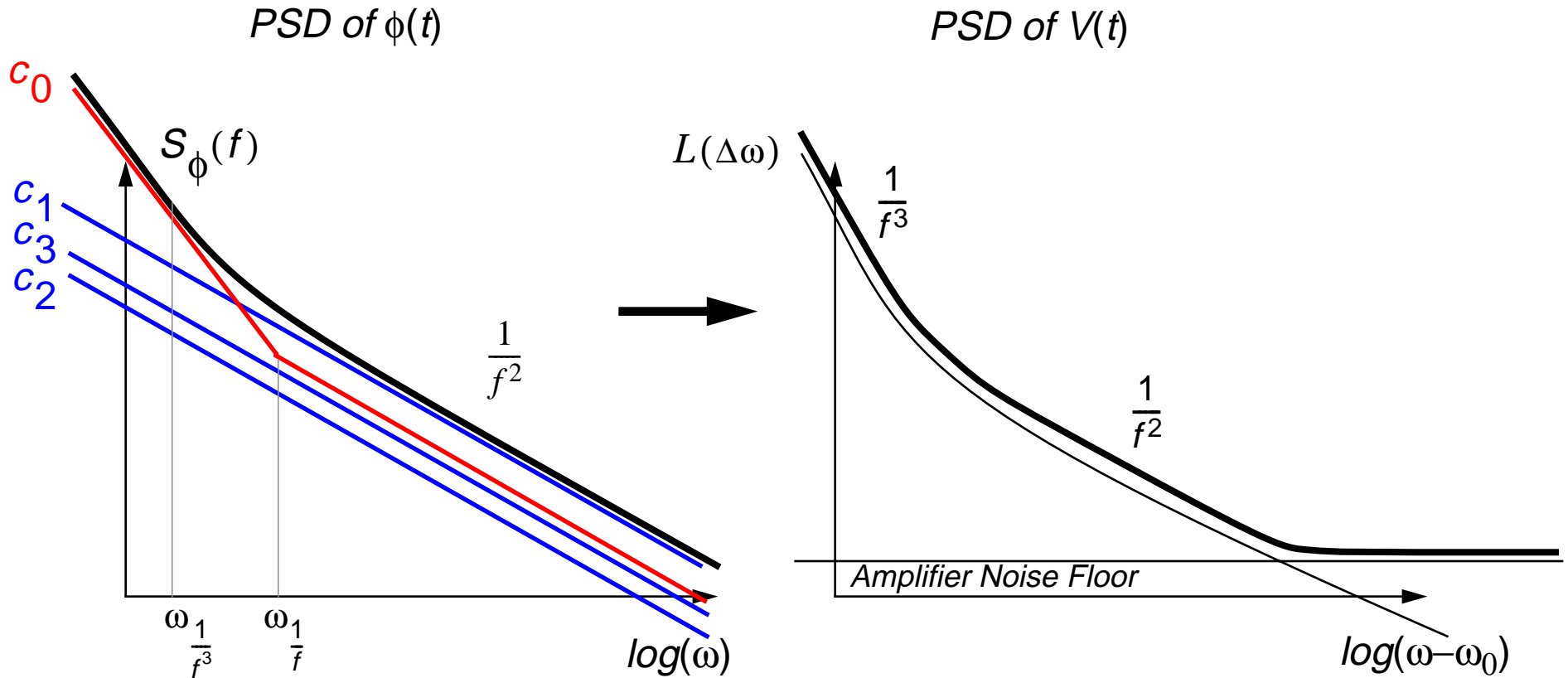


Noise Contributions from $n\omega_0$

$$\phi(t) = \frac{1}{q_{max}} \left[c_0 \int_{-\infty}^t i(\tau) d\tau + \sum_{n=1}^{\infty} c_n \int_{-\infty}^t i(\tau) \cos(n\omega\tau) d\tau \right]$$



Power Spectrum of Phase Noise



Noise components around integer multiples of the oscillation frequency have the strongest effect on phase noise, and their effect is weighted by the Fourier coefficients of the ISF, c_n .

Outline

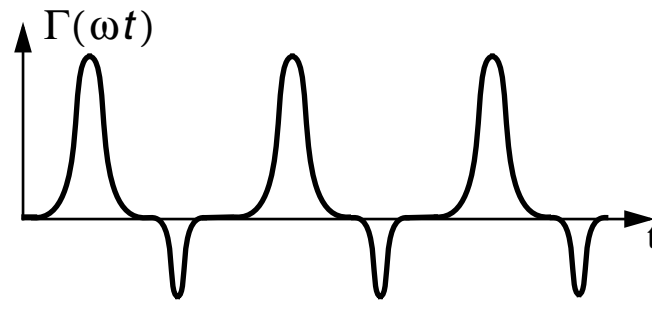
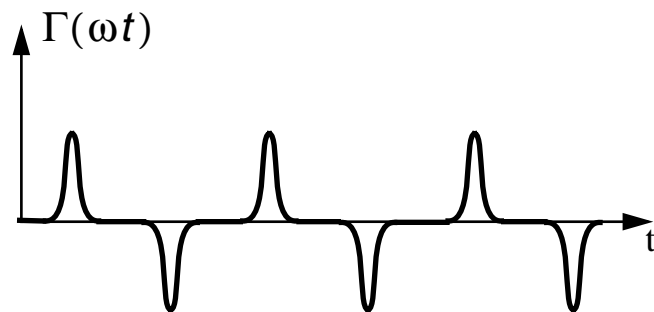
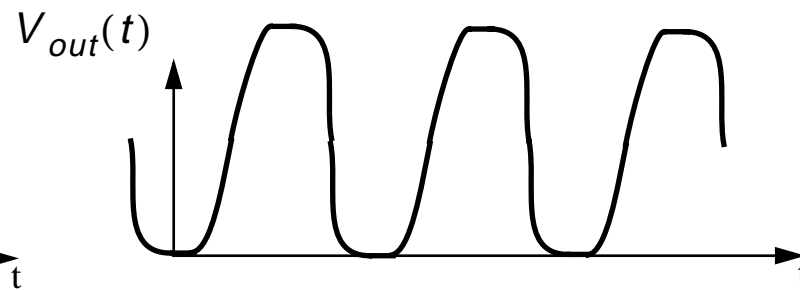
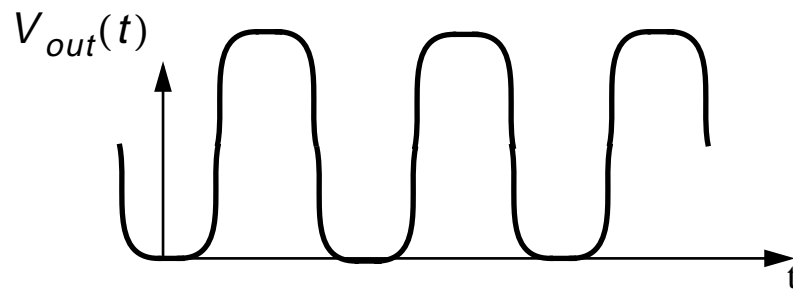
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Effect of Symmetry

$$c_0 = \frac{1}{2\pi} \int_0^{2\pi} \Gamma(x) dx$$

Symmetric rise and fall time

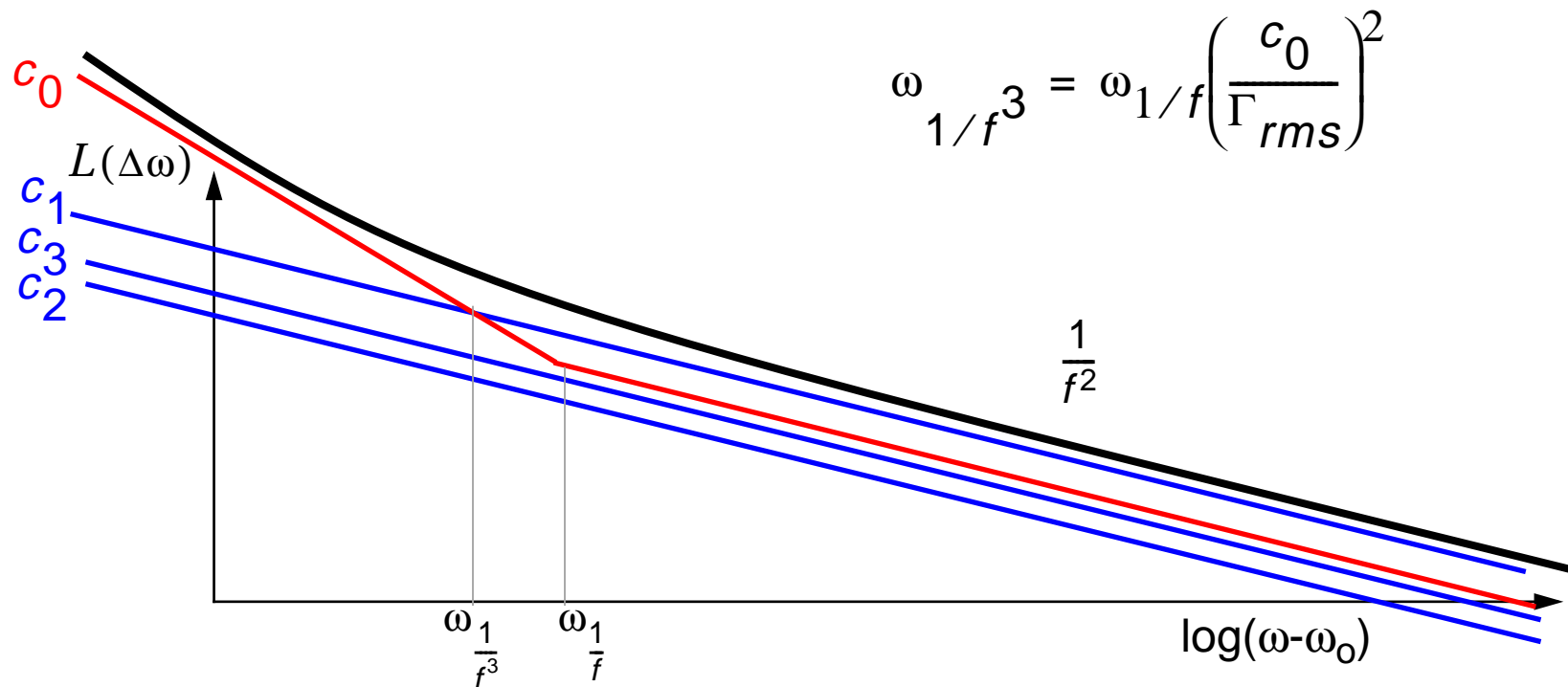
Asymmetric rise and fall time



The dc value of the ISF is governed by rise and fall time symmetry, and controls the contribution of low frequency noise to the phase noise.

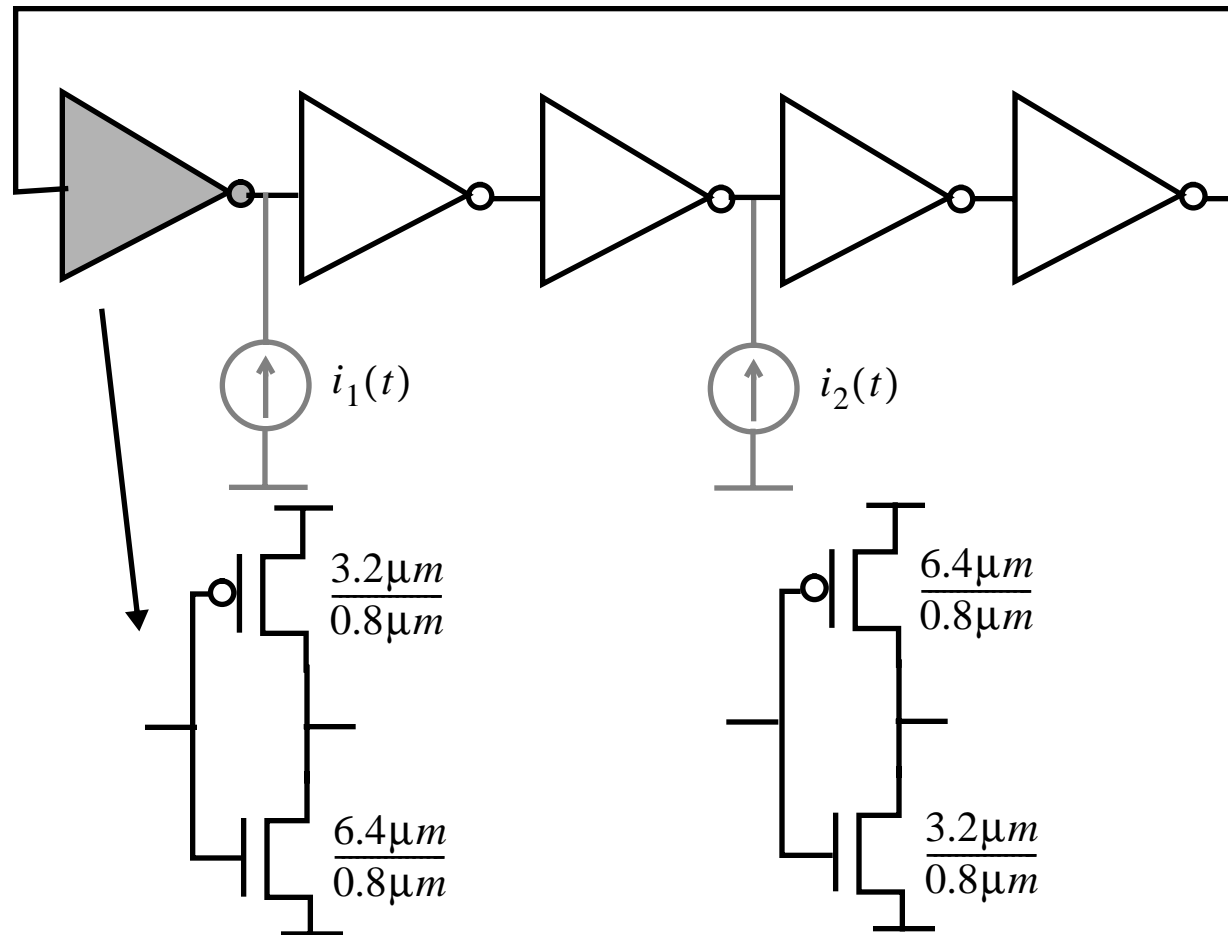
$1/f^3$ Corner of Phase Noise Spectrum

The $1/f^3$ corner of phase noise is NOT the same as $1/f$ corner of device noise



By designing for a symmetric waveform, the performance degradation due to low frequency noise can be minimized.

Ring Oscillator with an Asymmetric Stage

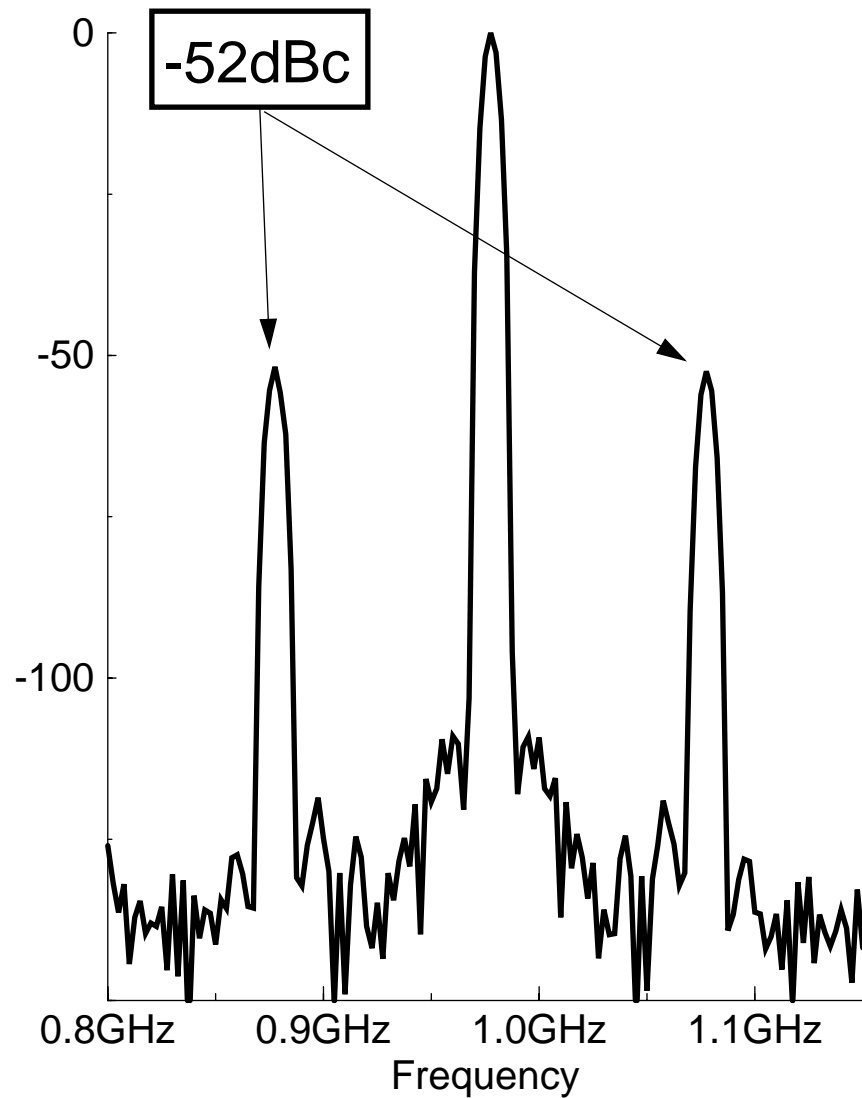
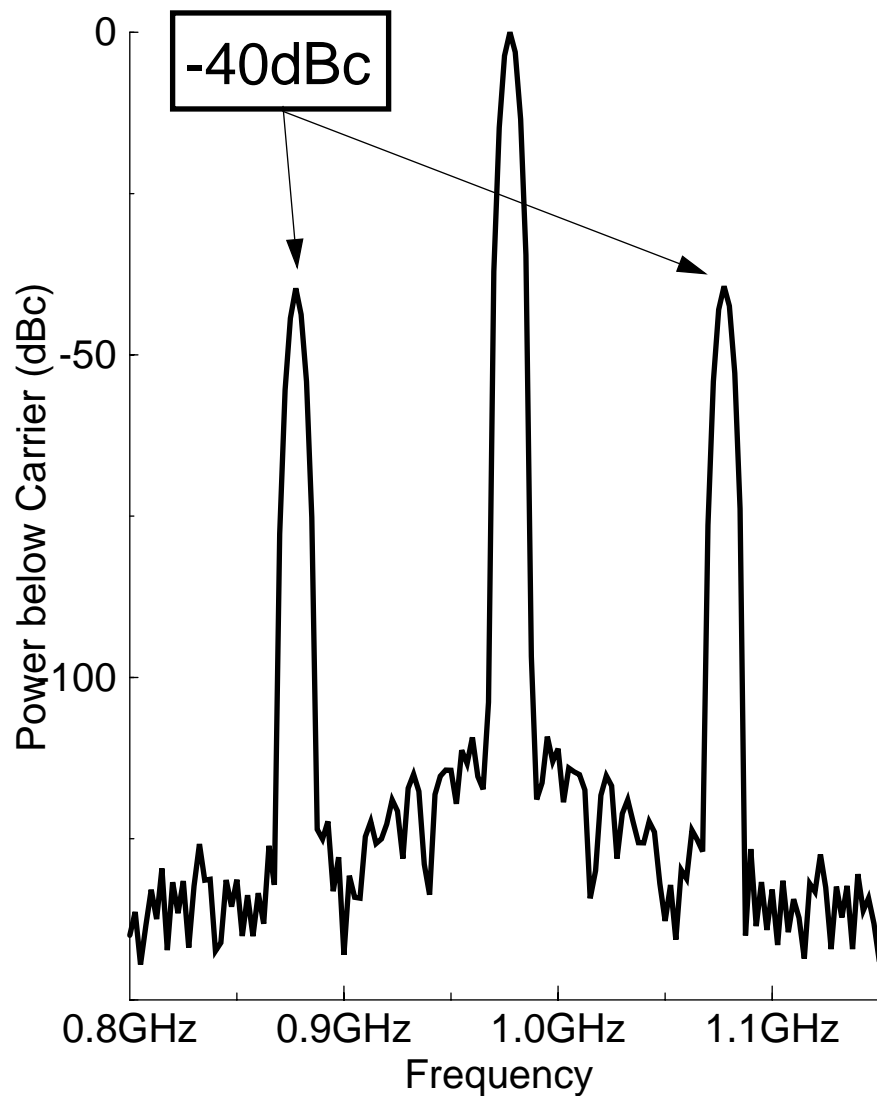


The effect of asymmetry can be seen by comparing the effect of low frequency injection into symmetric and asymmetric nodes.

Low Frequency Upconversion

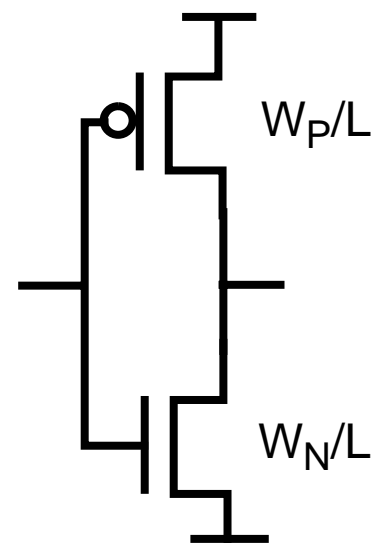
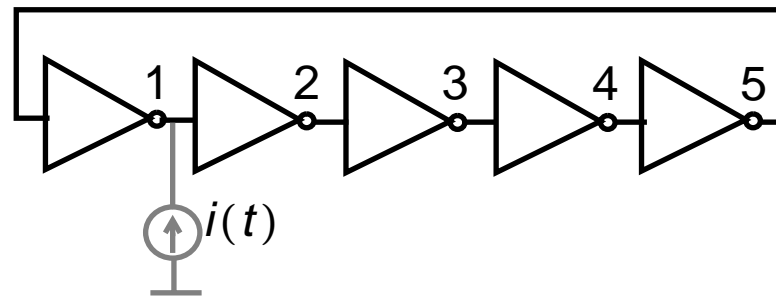
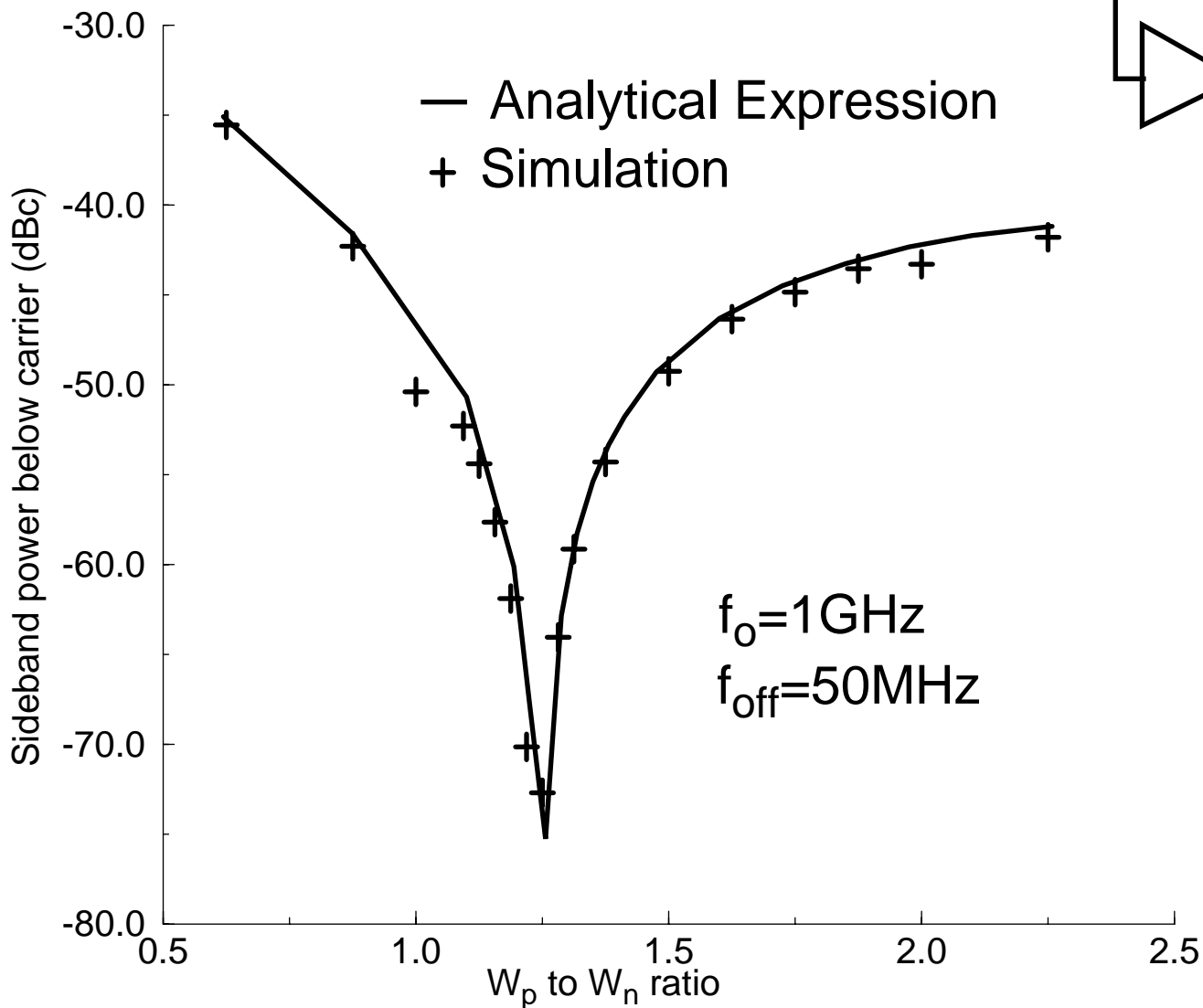
Injection into Asymmetric Node

Injection into Symmetric Node

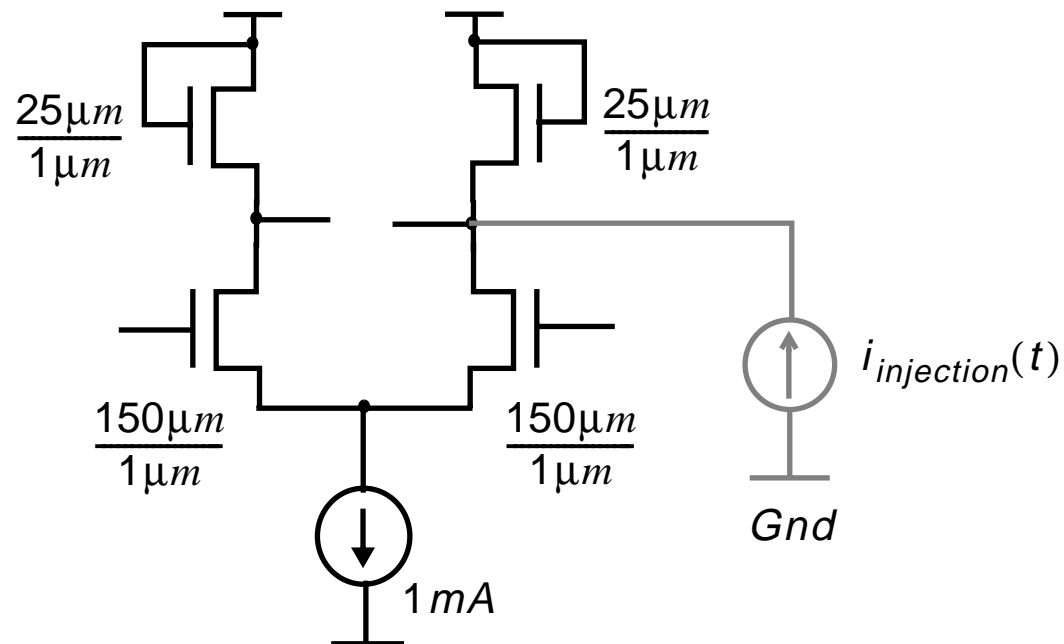
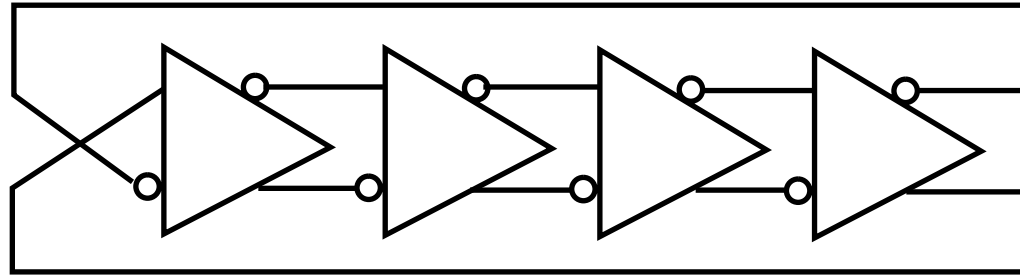


Effect of Rise and Fall Time Symmetry

Sidebands Due to Low Frequency Injection



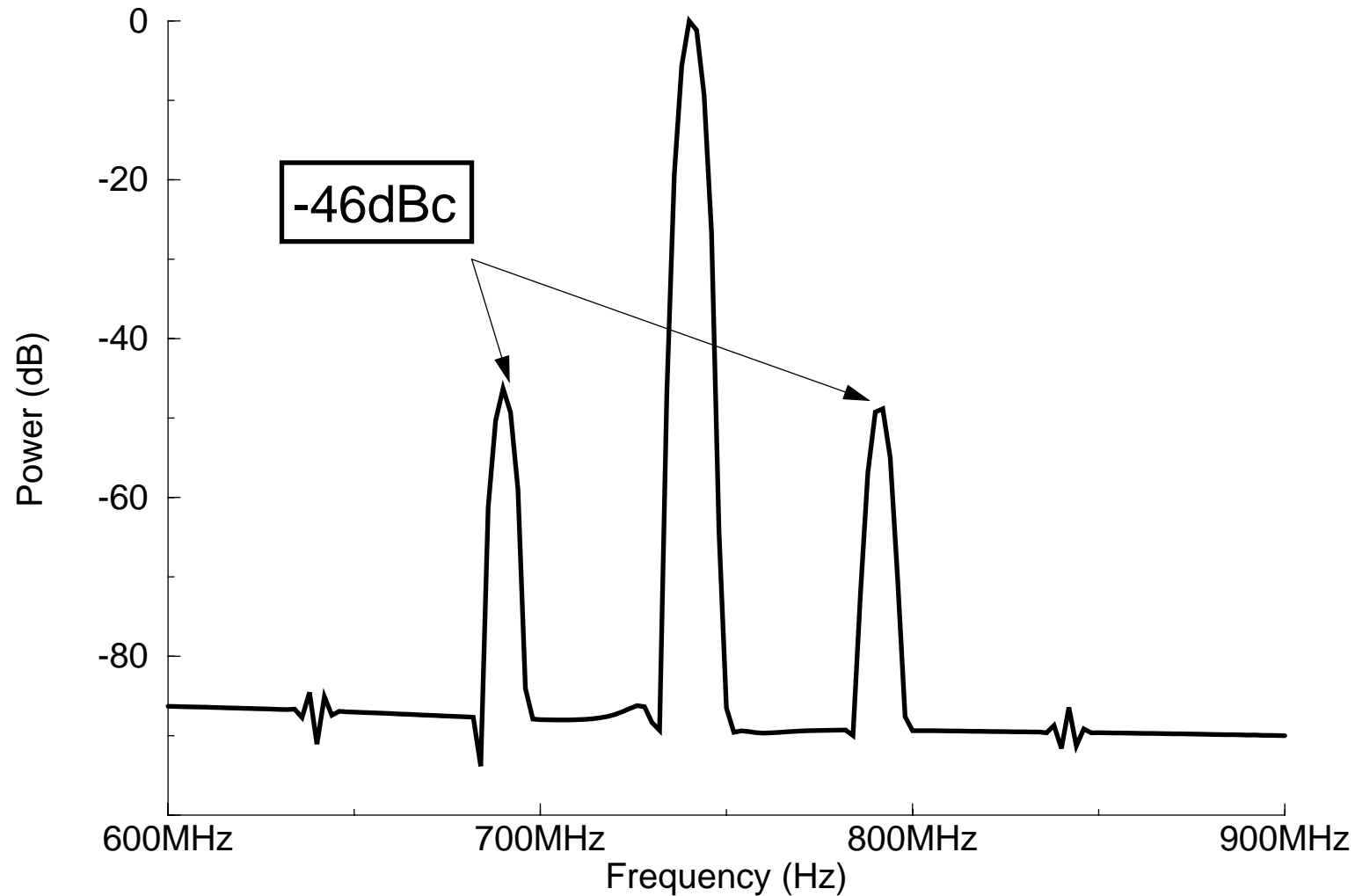
Effect of Differential Symmetry



*The noise sources on each of the differential nodes are not fully correlated.
It is the symmetry of the half circuit that matters.*

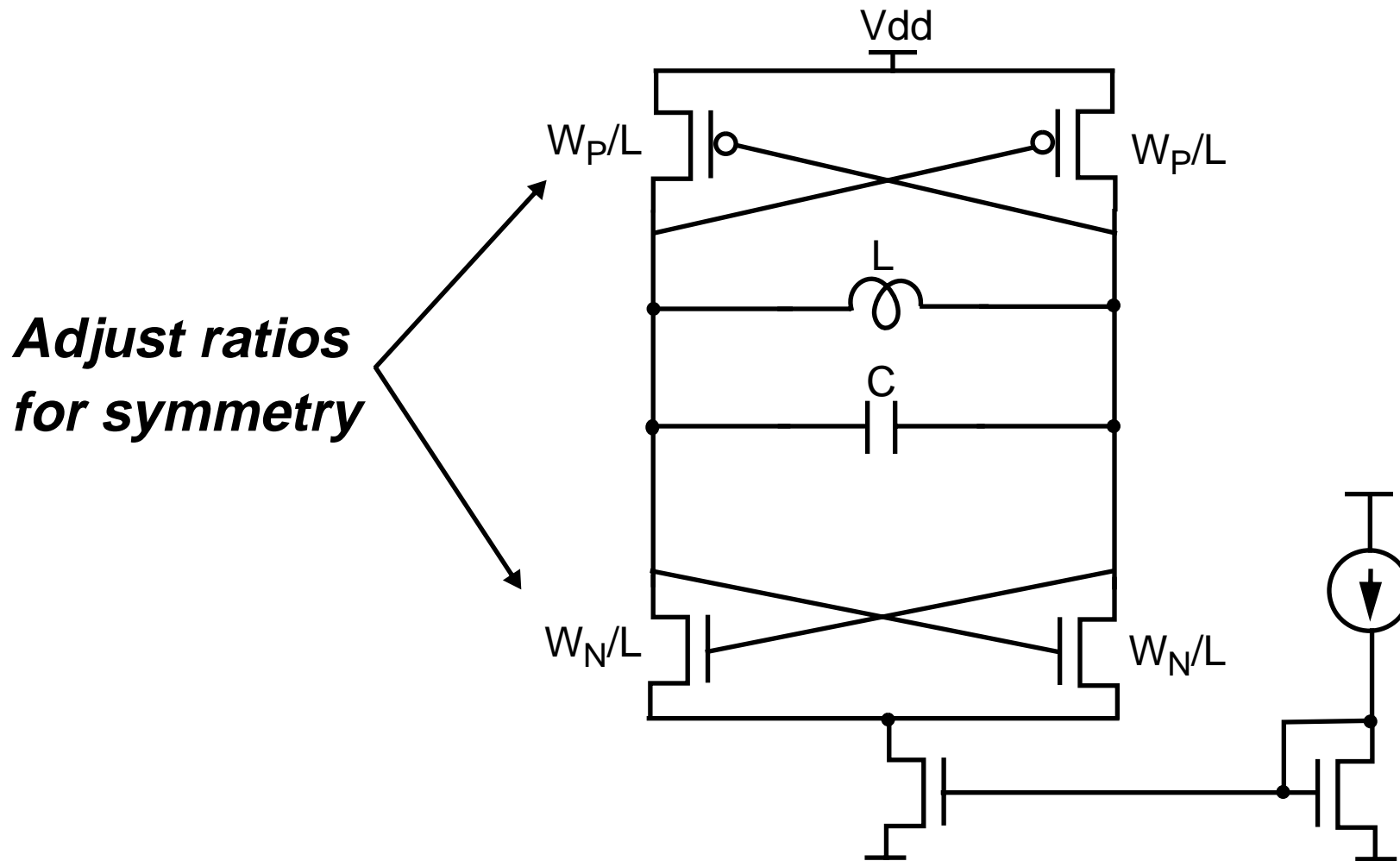
Effect of Differential Symmetry

Low Frequency Current Injection into Differential Ring



Differential symmetry does not automatically eliminate the low frequency upconversion.

A Symmetric LC Oscillator

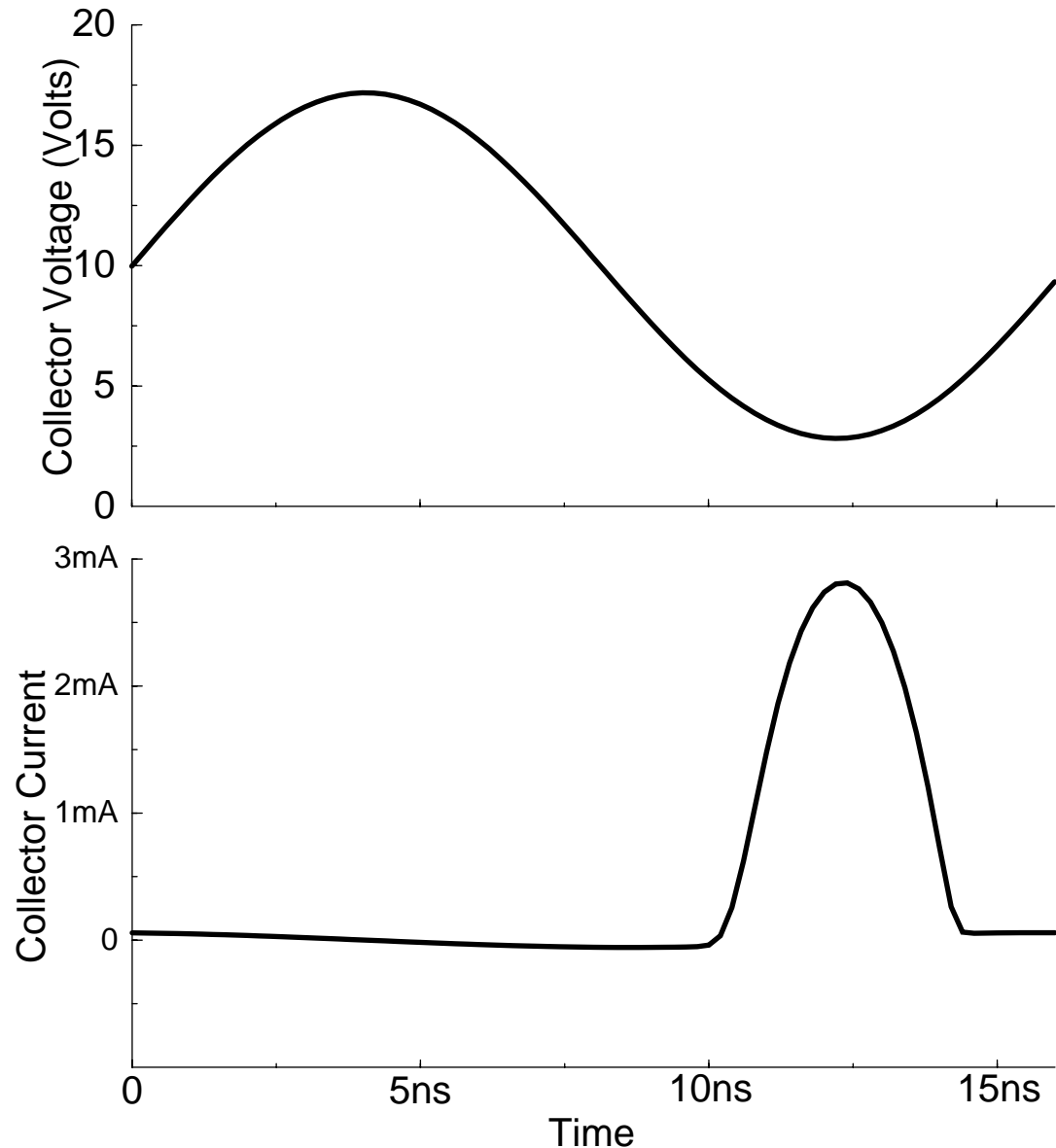
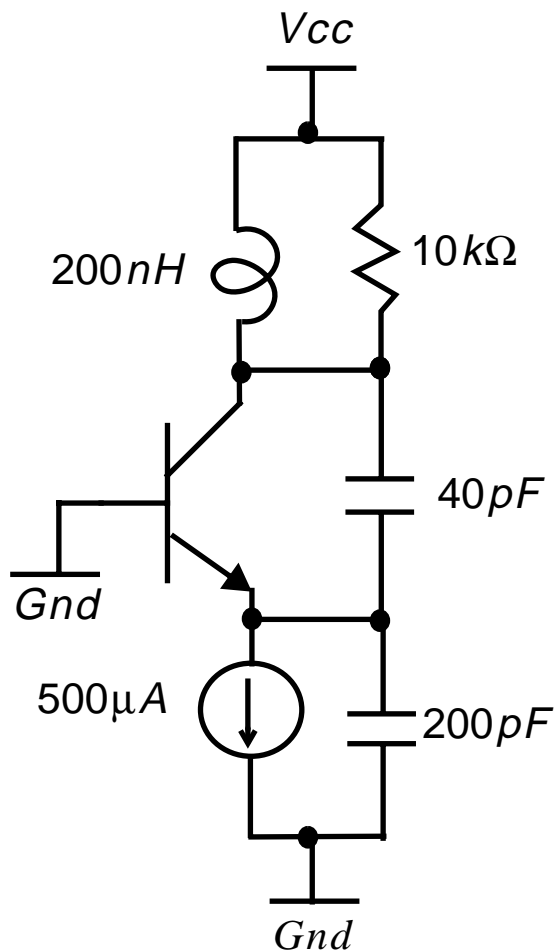


Possible to Adjust Symmetry Properties of the Waveform

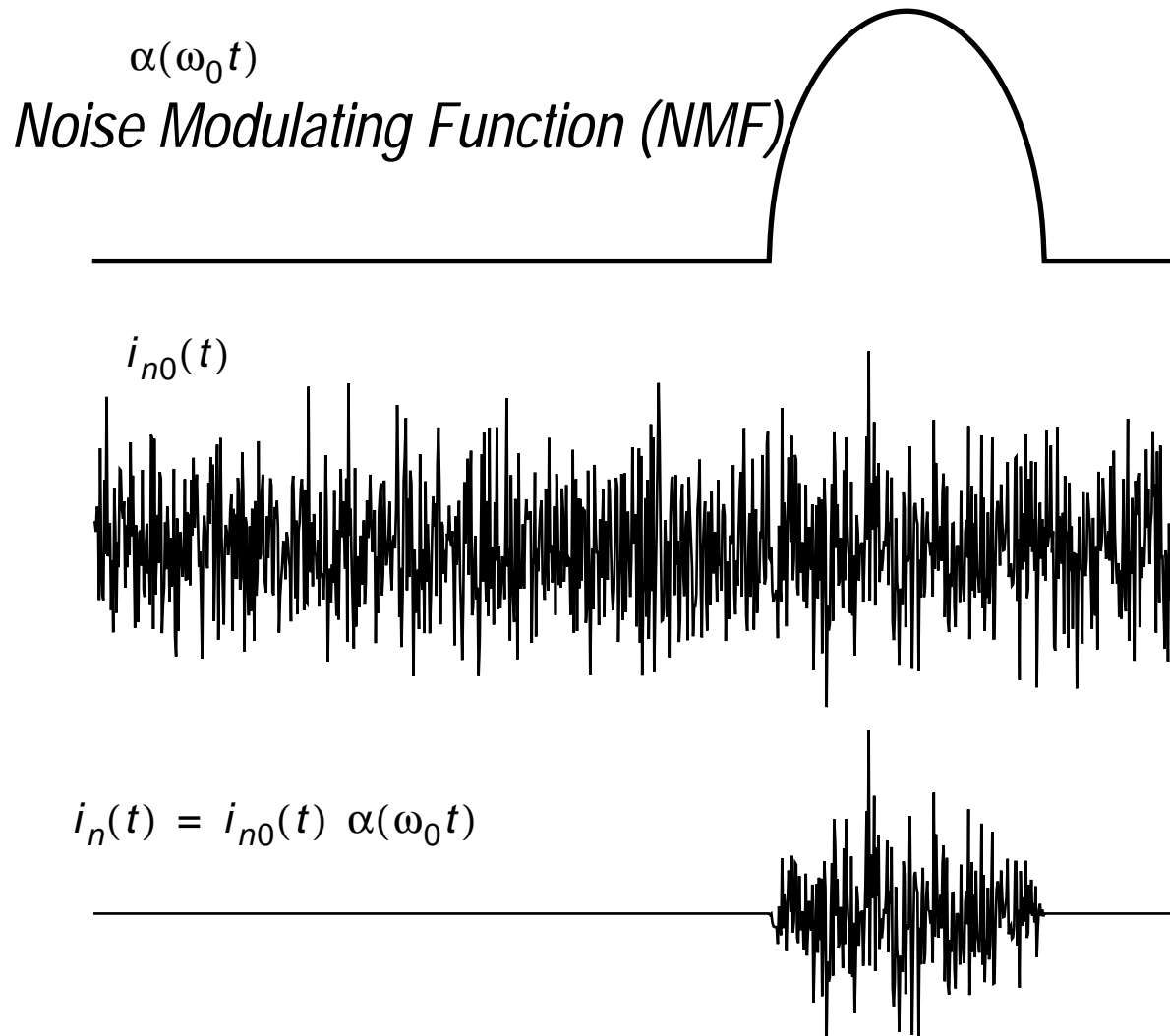
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Time Varying Current in Colpitts Oscillator



Cyclostationary Properties, Time Domain



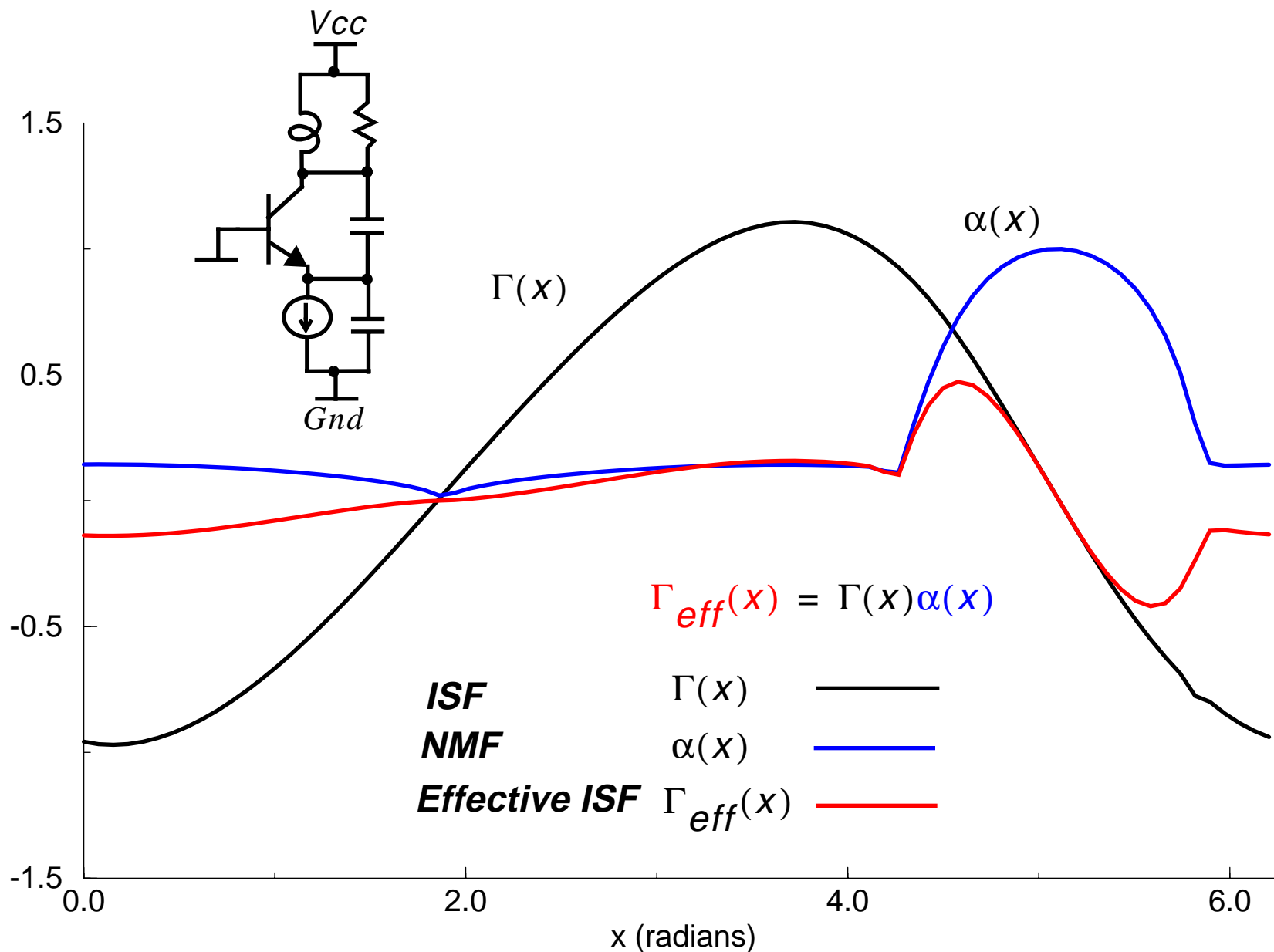
$$\begin{aligned}\phi(t) &= \int_{-\infty}^t i_n(\tau) \frac{\Gamma(\omega_0 \tau)}{q_{max}} d\tau \\ &= \int_{-\infty}^t i_{n0}(\tau) \frac{\alpha(\omega_0 \tau) \Gamma(\omega_0 \tau)}{q_{max}} d\tau\end{aligned}$$

Effective ISF:

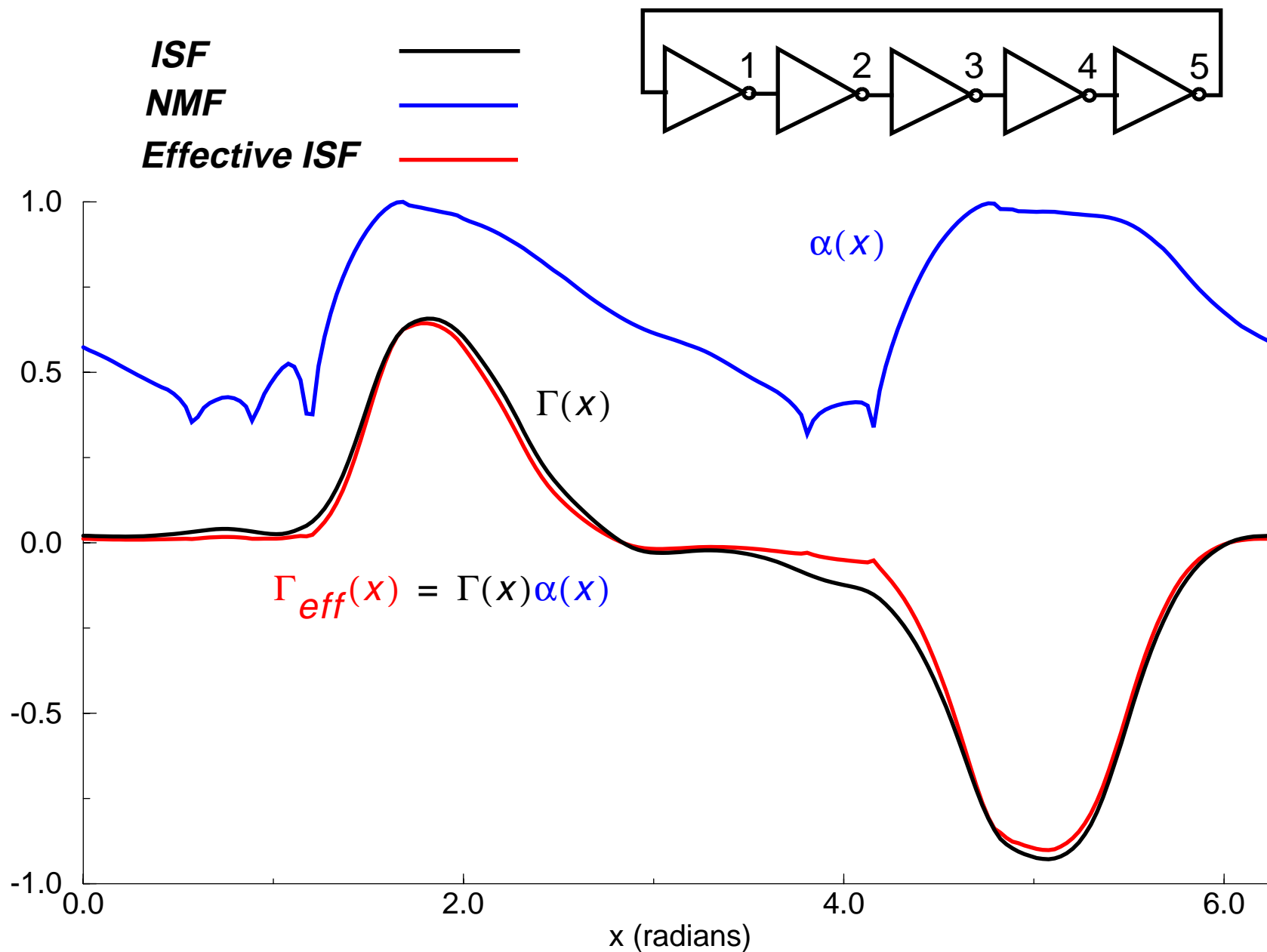
$$\Gamma_{eff}(x) = \Gamma(x) \cdot \alpha(x)$$

A cyclostationary source can be modeled as stationary with a new ISF.

Colpitts Oscillator



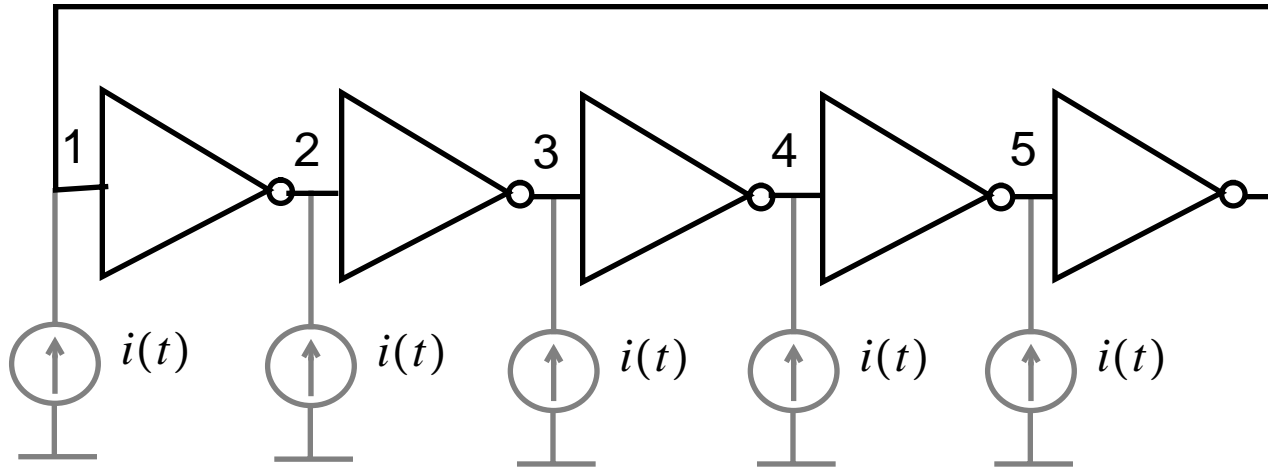
5 Stage Ring Oscillator



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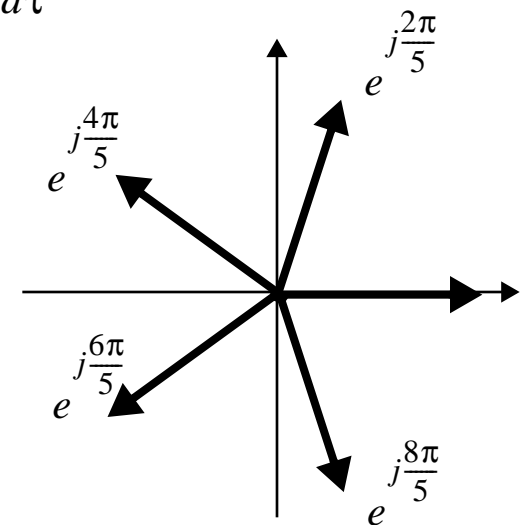
Fully Correlated Sources



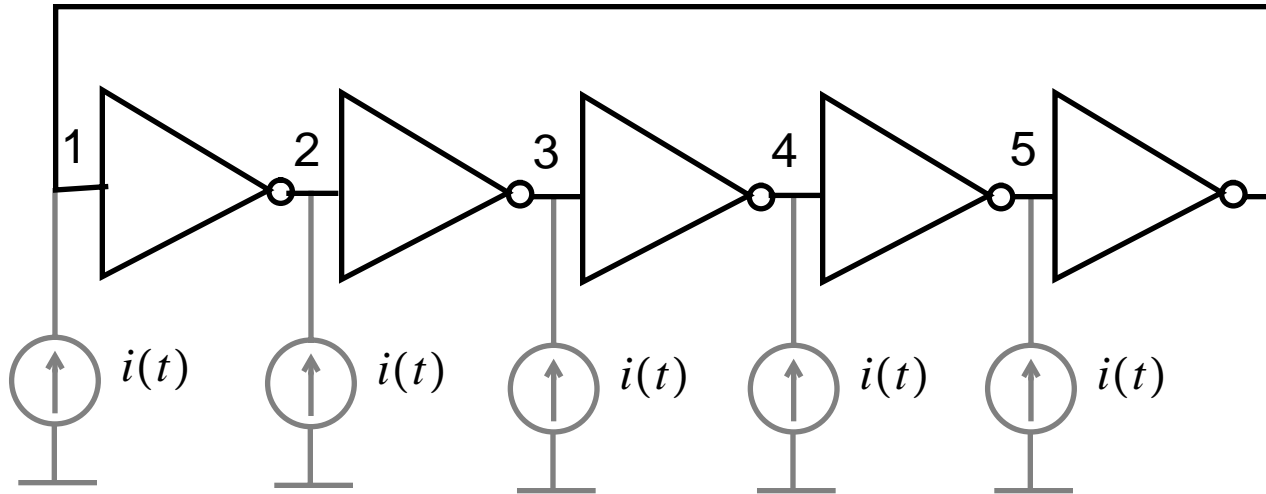
Superposition:
$$\phi_{total}(t) = \sum_{k=1}^N \phi(t) = \int_{-\infty}^t \frac{i(\tau)}{q_{max}} \left[\sum_{k=1}^N \Gamma_k(\omega_0 \tau) \right] d\tau \approx \frac{Nc_0}{q_{max}} \int_{-\infty}^t i(\tau) d\tau$$

Similar stages:
$$\Gamma_k(\omega_0 t) = \Gamma\left(\omega_0 t + \frac{2\pi k}{N}\right)$$

$$\sum_{k=1}^N \Gamma_k(\omega_0 \tau) \approx Nc_0$$



Fully Correlated Sources



$$\phi_{total}(t) \approx \frac{Nc_0}{q_{max}} \int_{-\infty}^t i(\tau) d\tau$$

Only the low frequency portion of substrate and supply noise is important, provided:

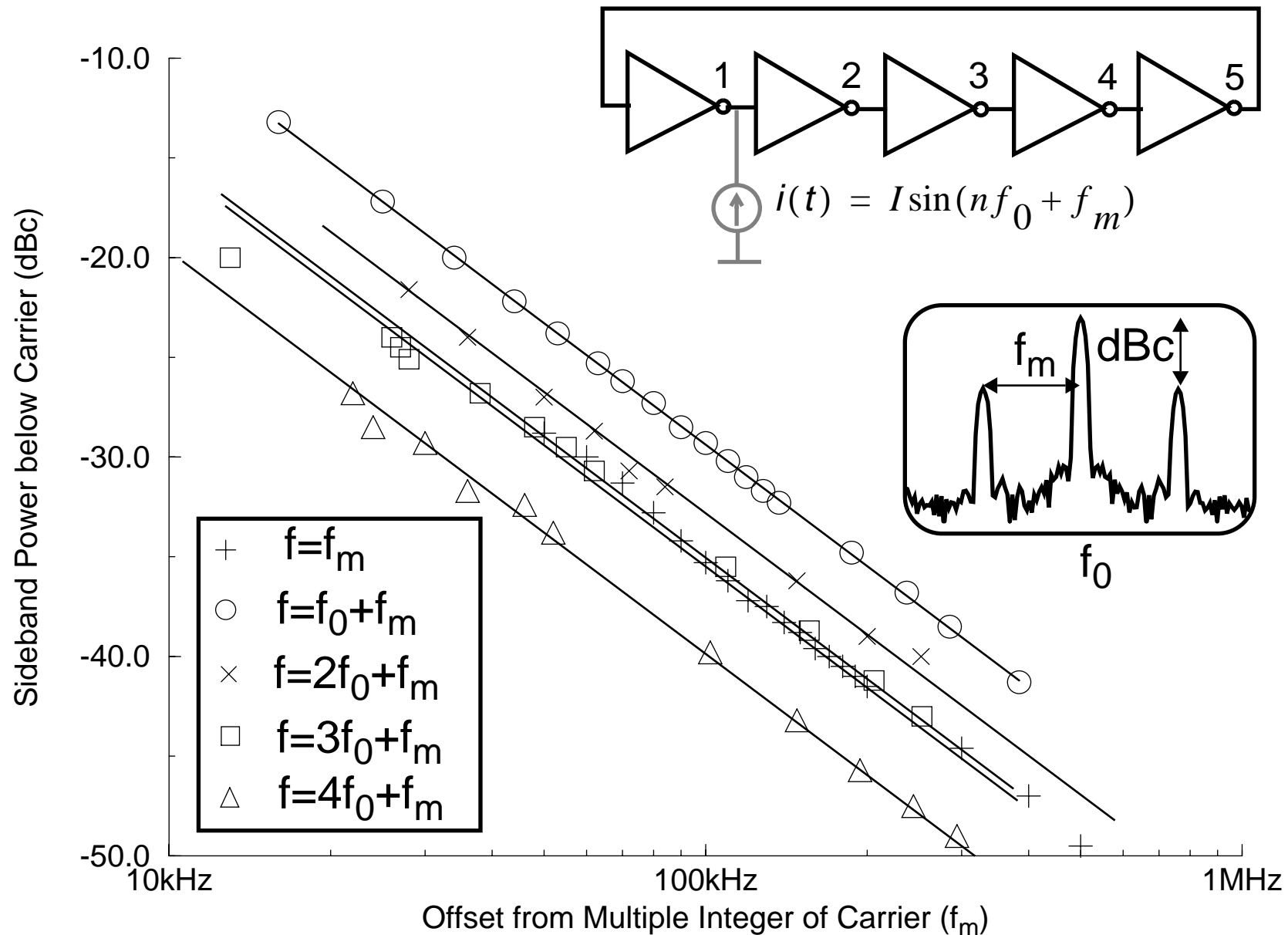
1. Stages and loadings are the same
2. The noise sources are identical

This is good news since c_0 can be significantly reduced by adjusting the symmetry.

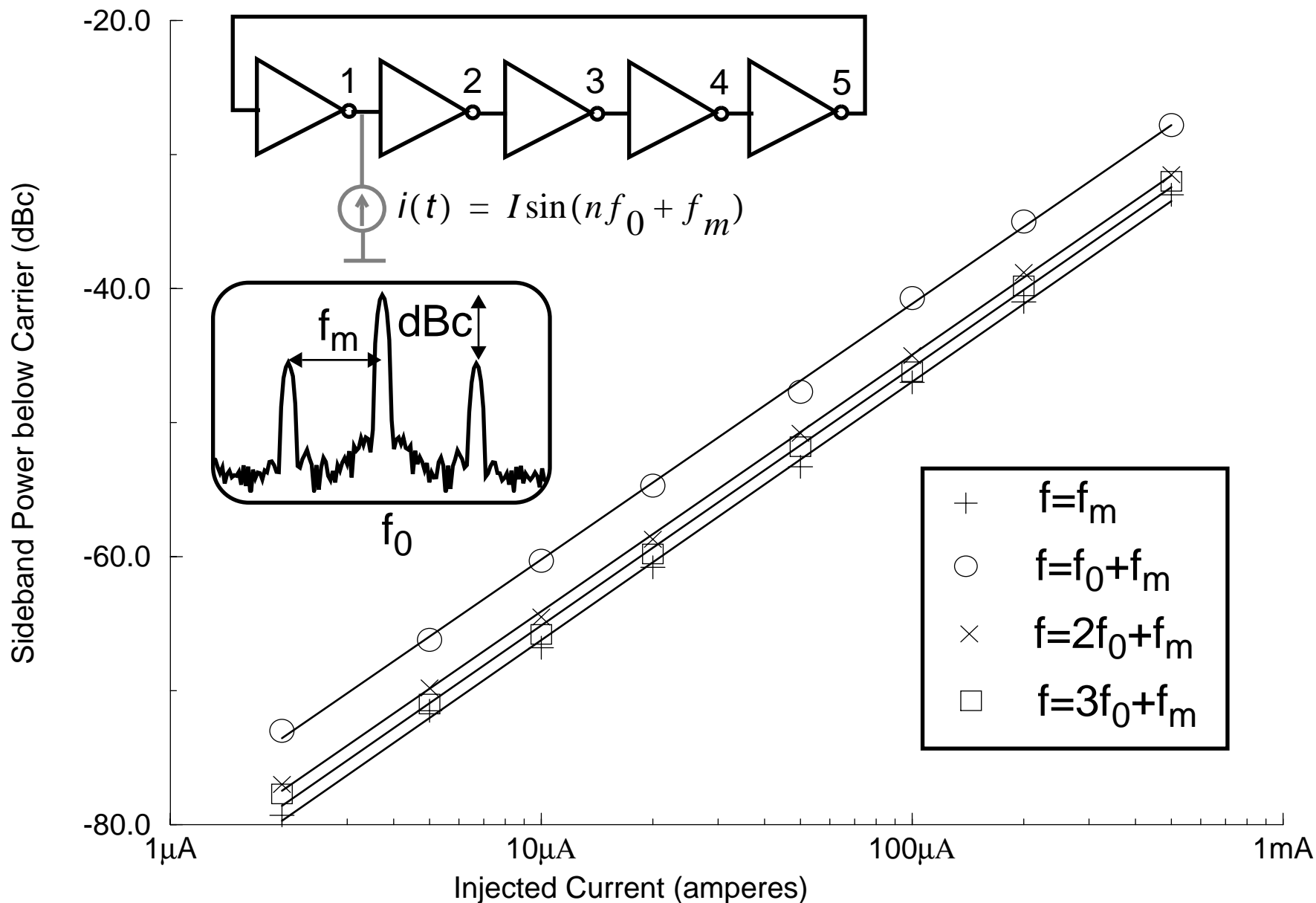
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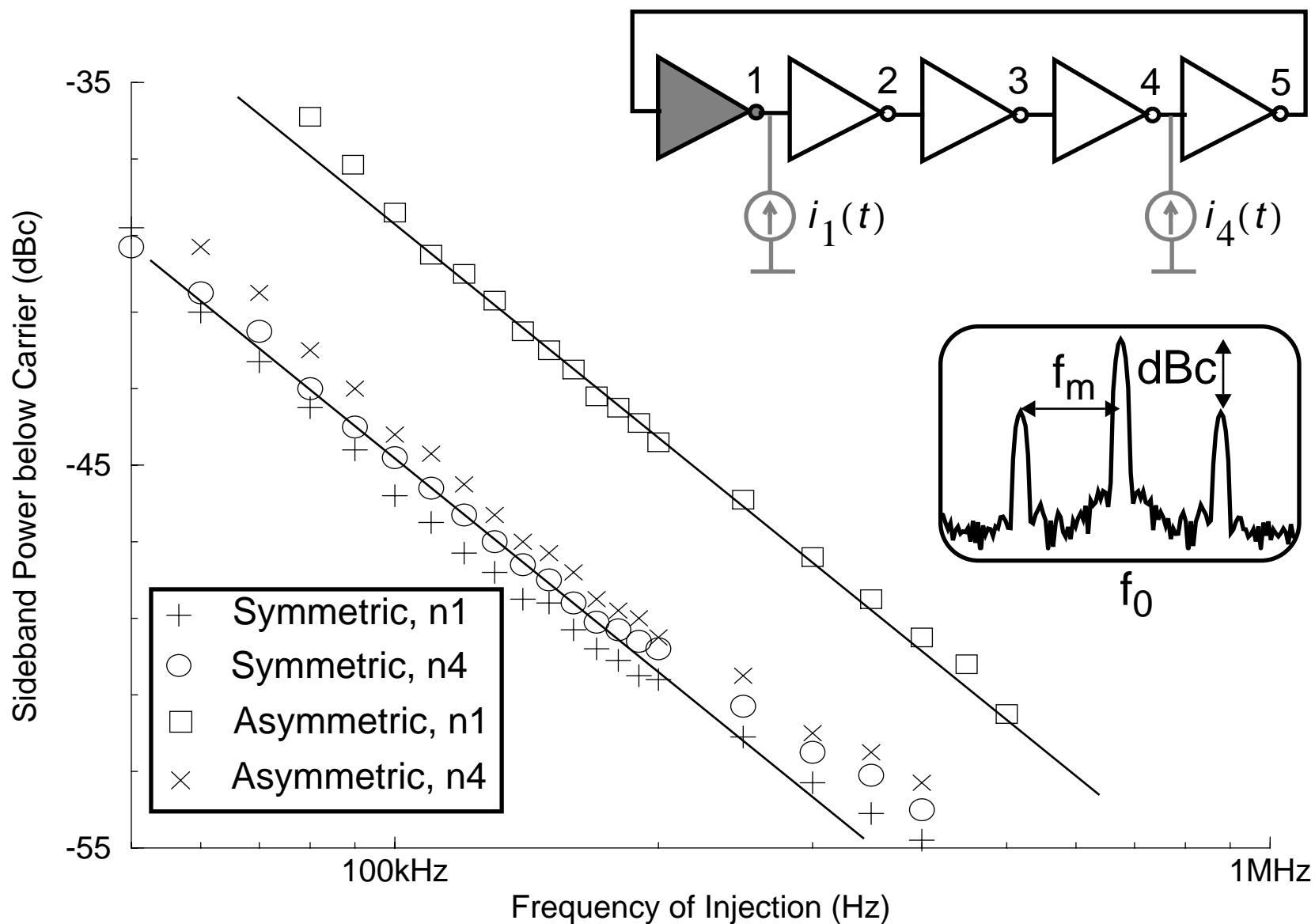
Injection at Integer Multiples of f_0



Sideband Power vs. Injection Current

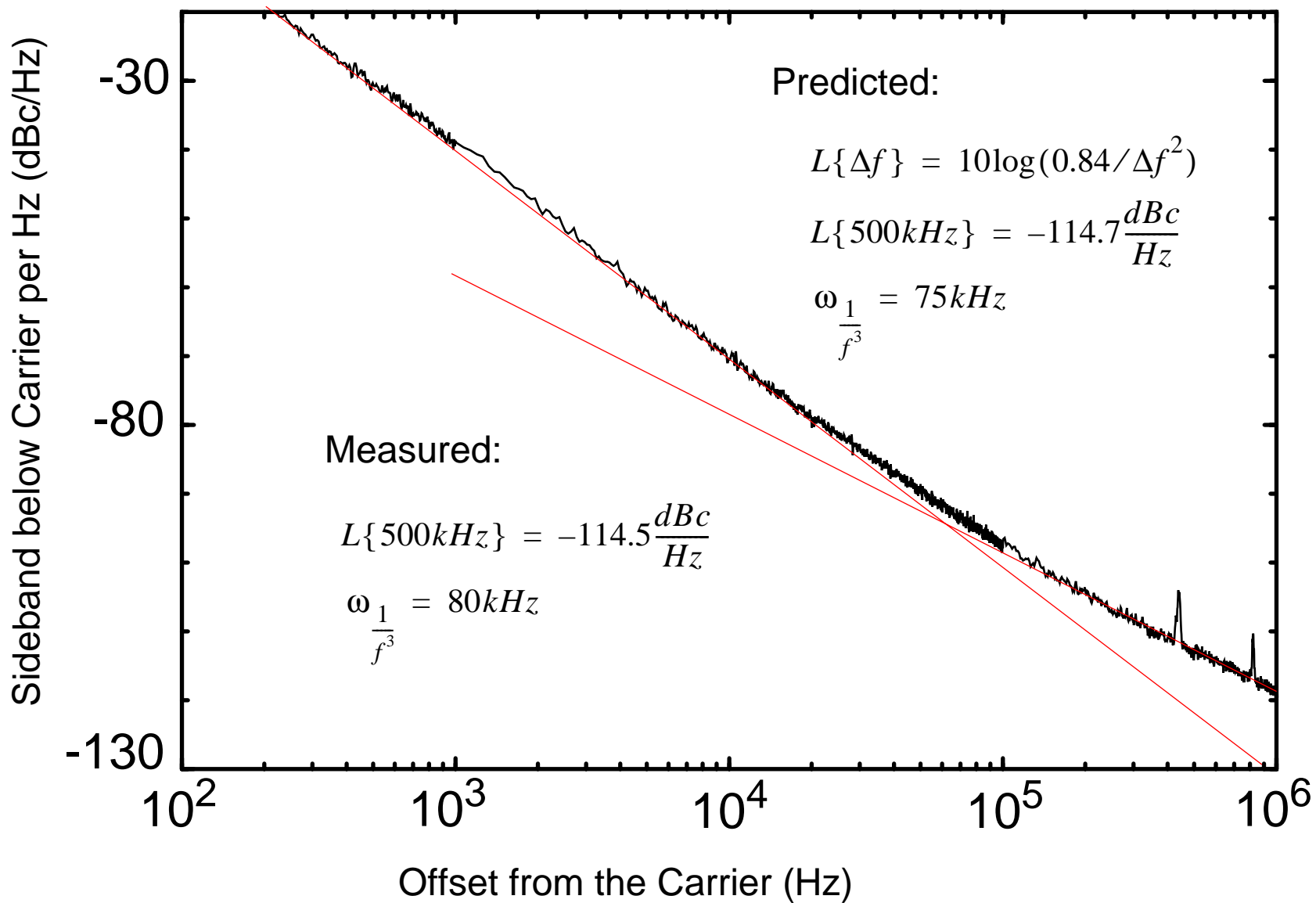


Symmetric vs. Asymmetric Ring Oscillator



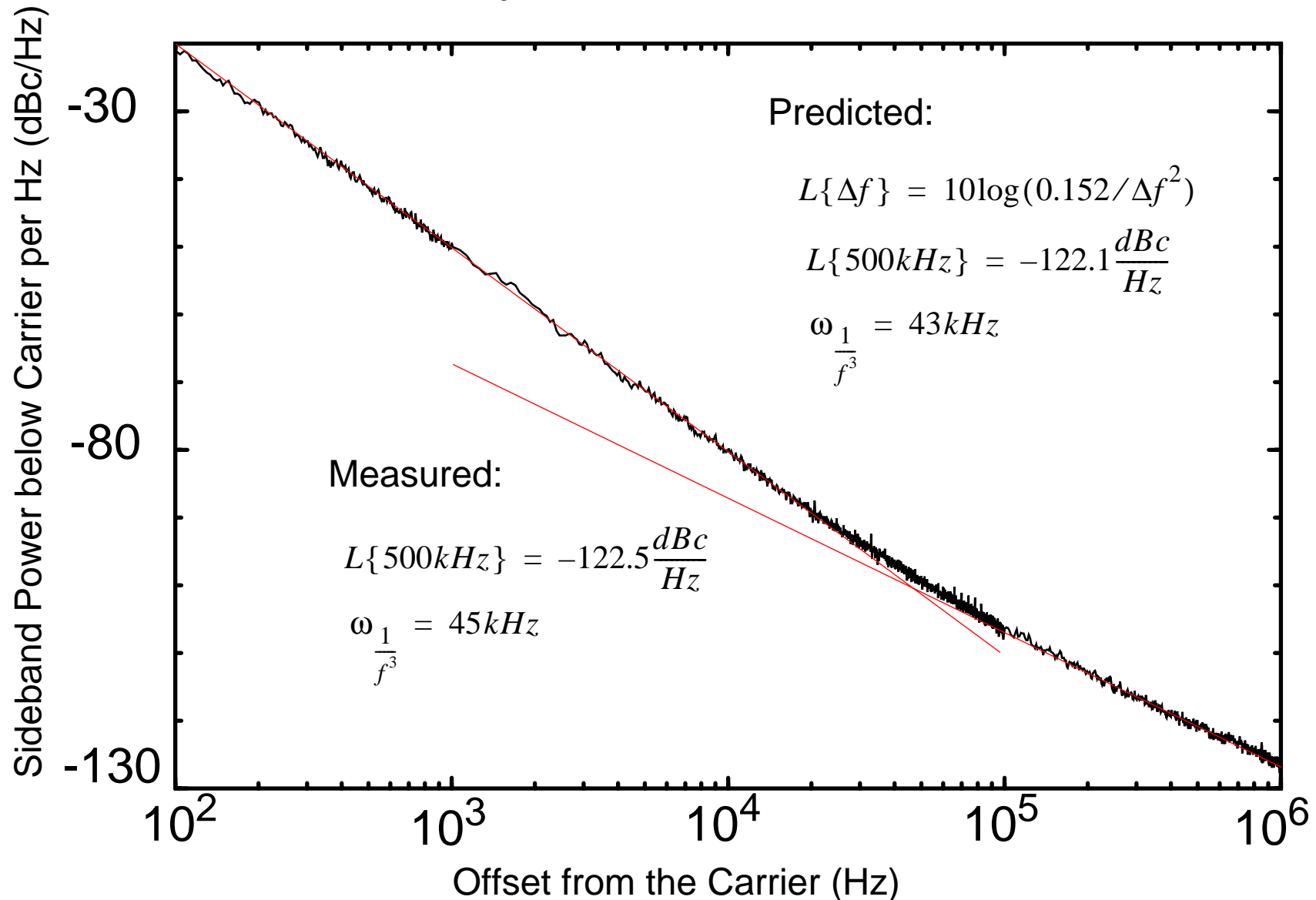
5-Stage Single-Ended Ring Oscillator

$f_0=232\text{MHz}$, $2\mu\text{m}$ Technology



11-Stage Single-Ended Ring Oscillator

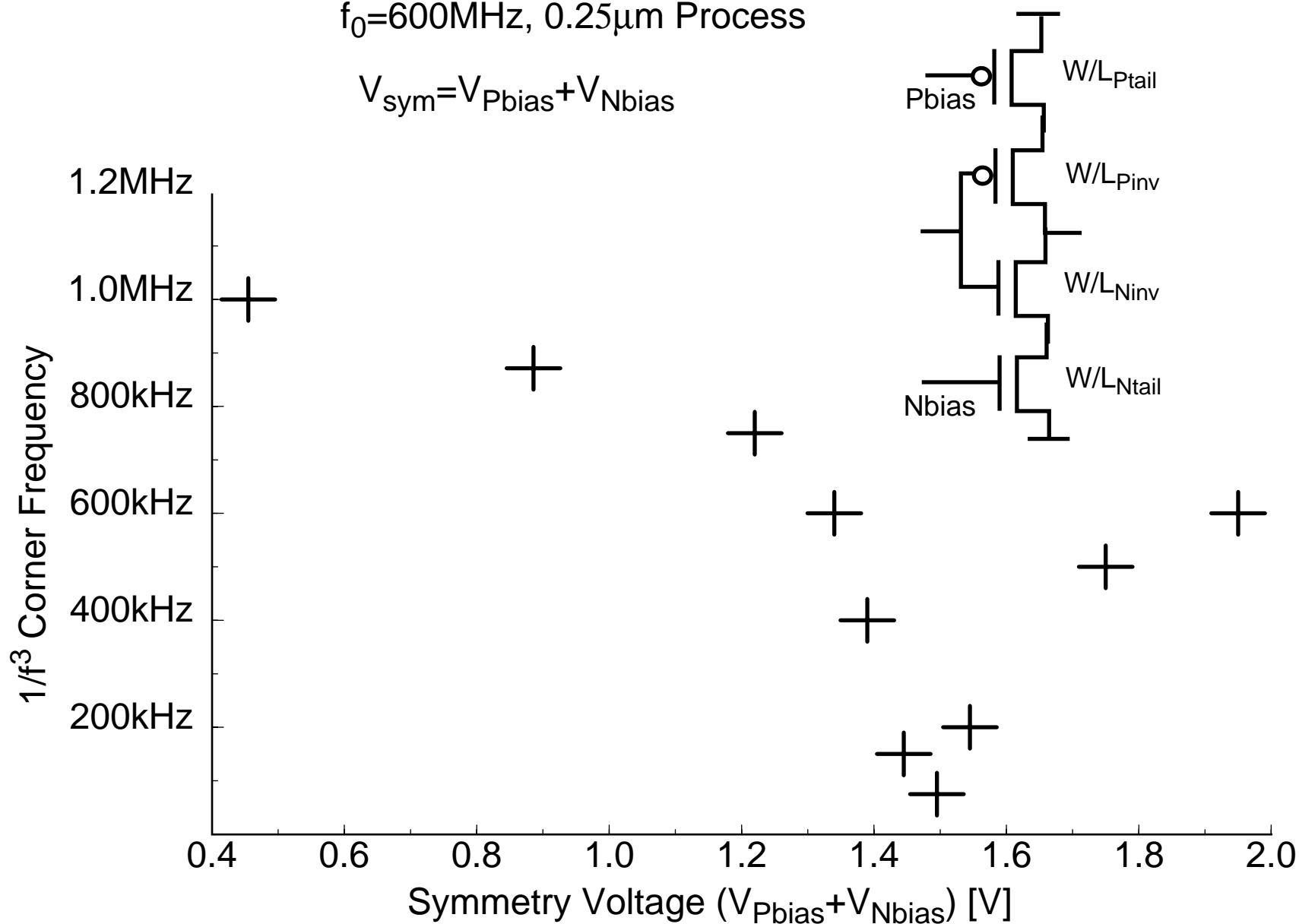
$f_0=115\text{MHz}$, $2\mu\text{m}$ Process



9-Stage Current Starved Single-Ended VCO

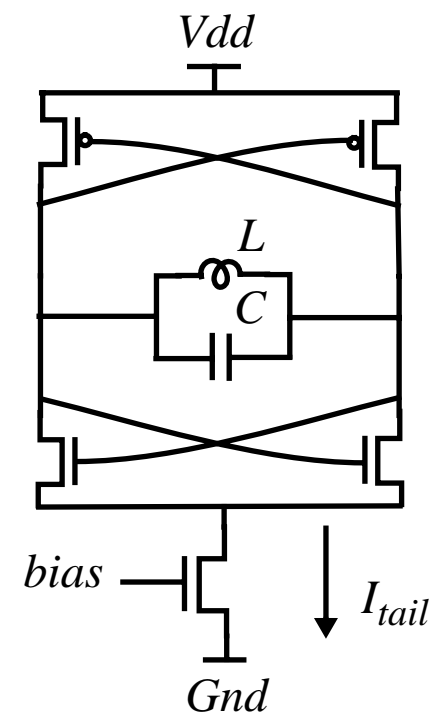
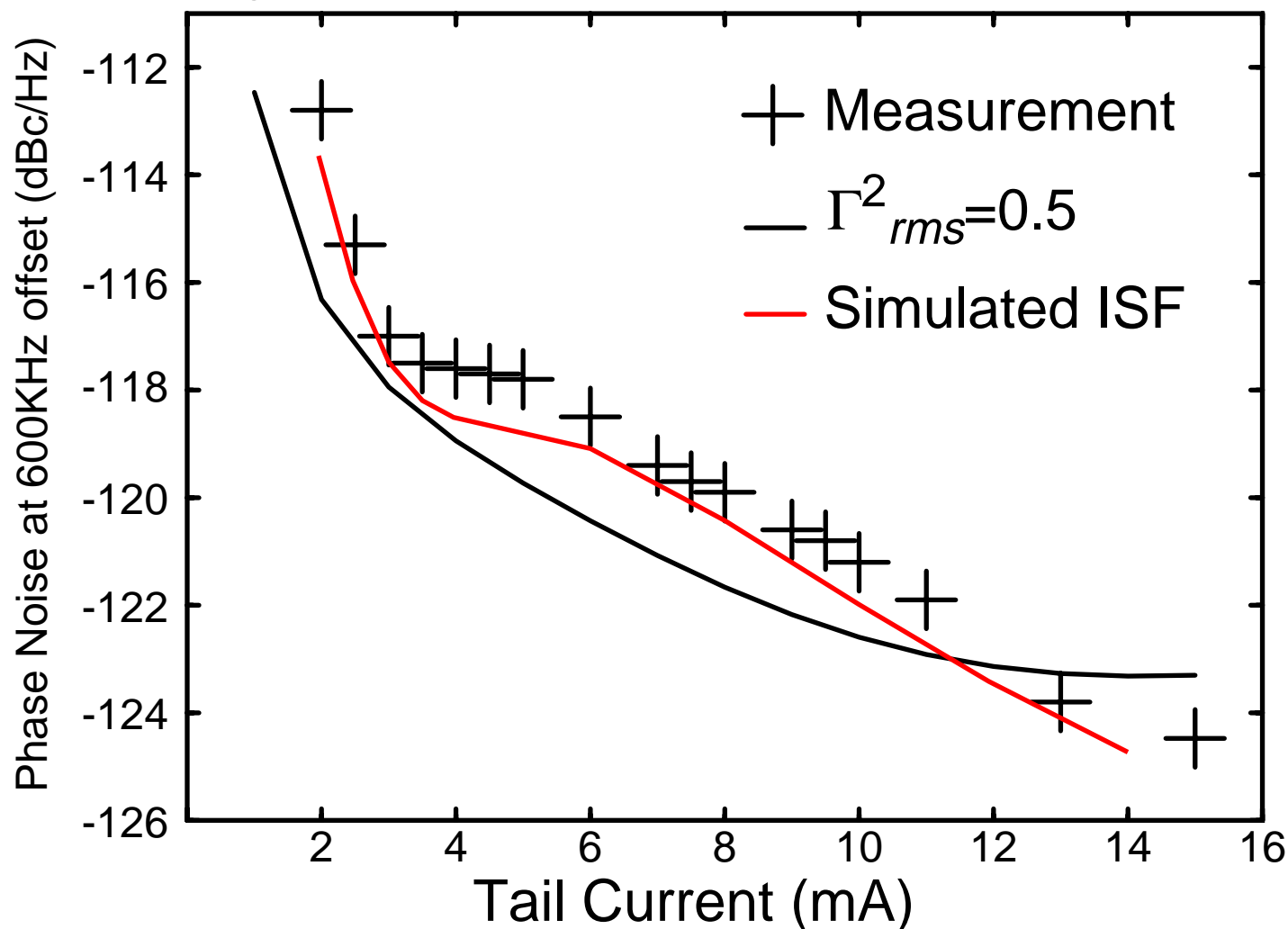
$f_0=600\text{MHz}$, $0.25\mu\text{m}$ Process

$$V_{\text{sym}} = V_{\text{Pbias}} + V_{\text{Nbias}}$$



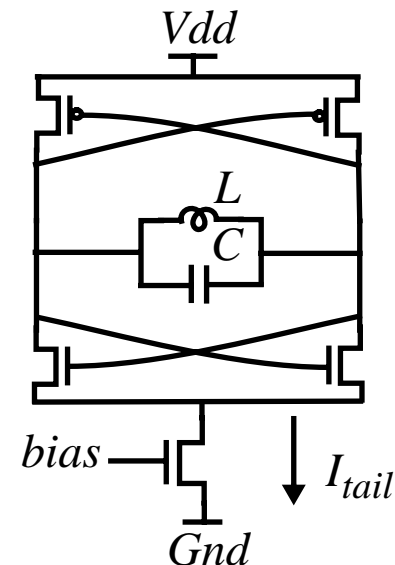
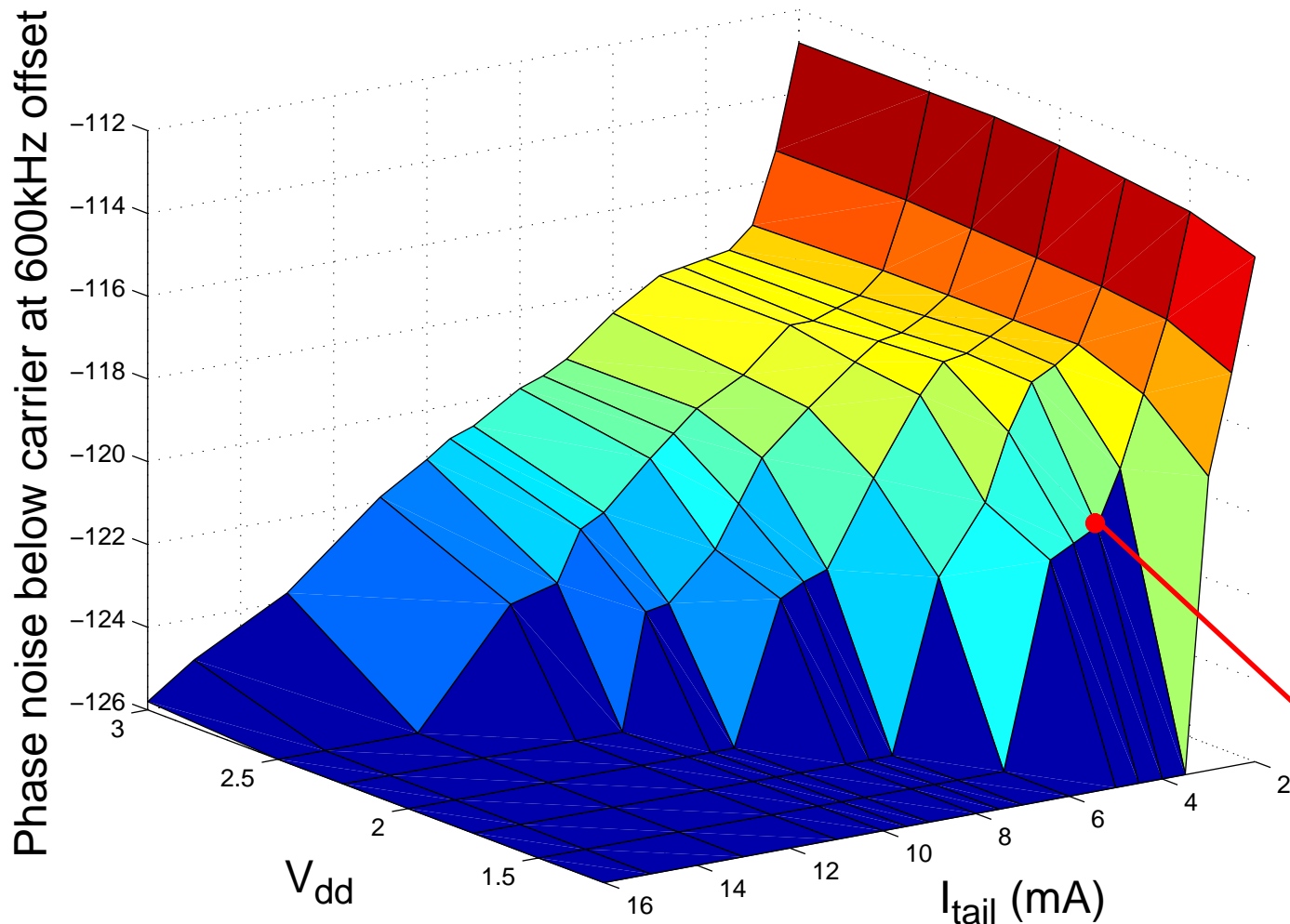
Complementary Cross-Coupled LC Oscillator

$f_0=1.8\text{GHz}$, $0.25\mu\text{m}$ Process ($V_{DD}=3\text{V}$)



Complementary Cross-Coupled VCO

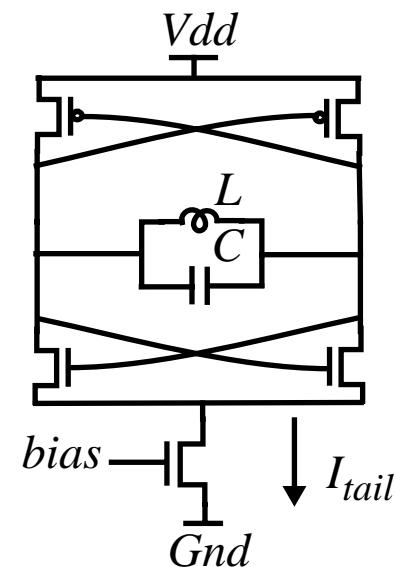
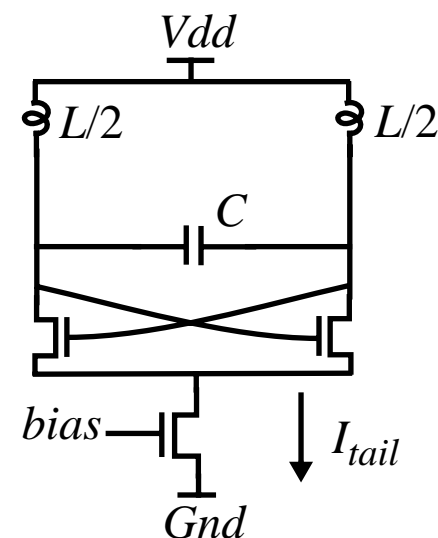
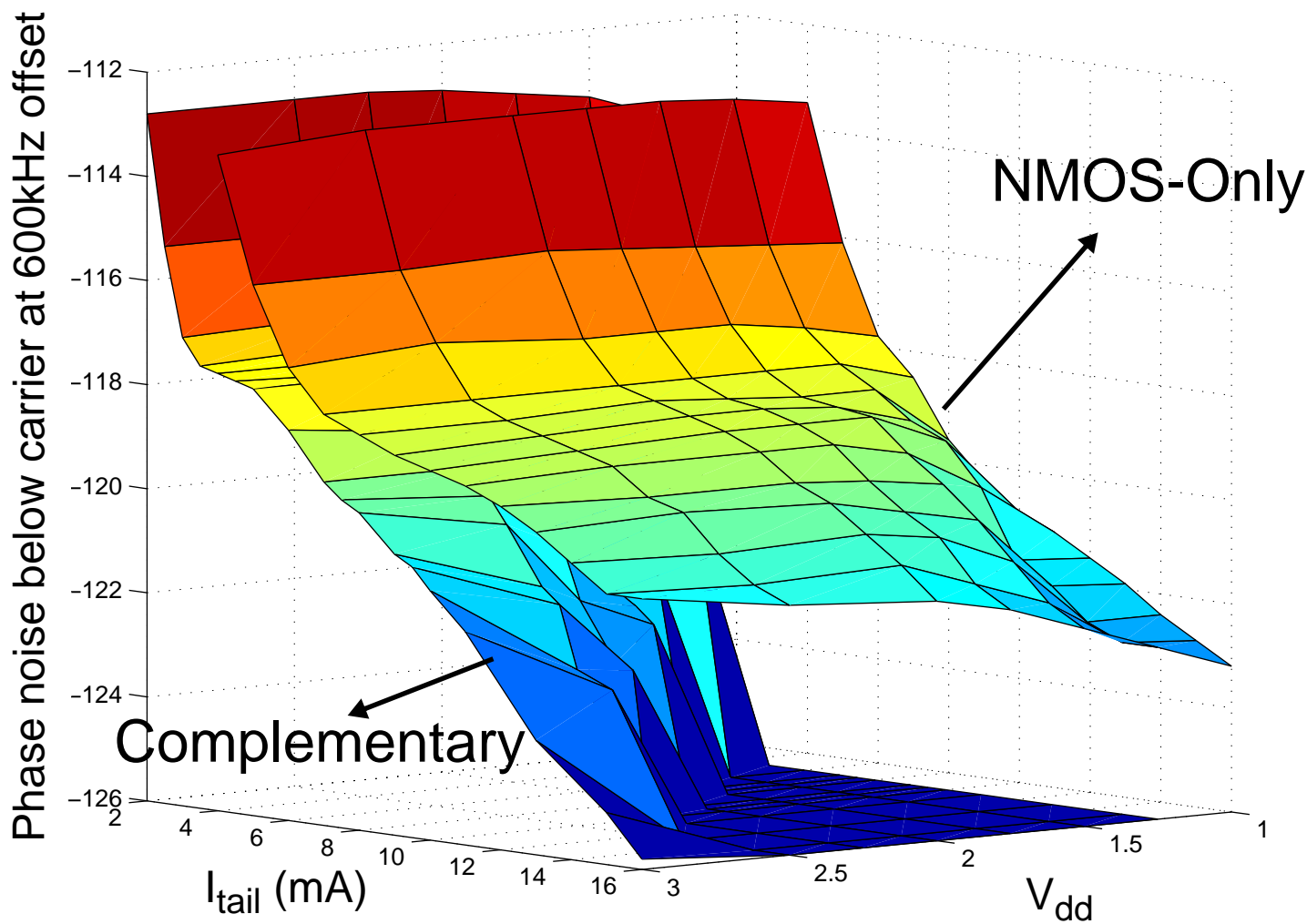
$f_0=1.8\text{GHz}$, $0.25\mu\text{m}$ Process



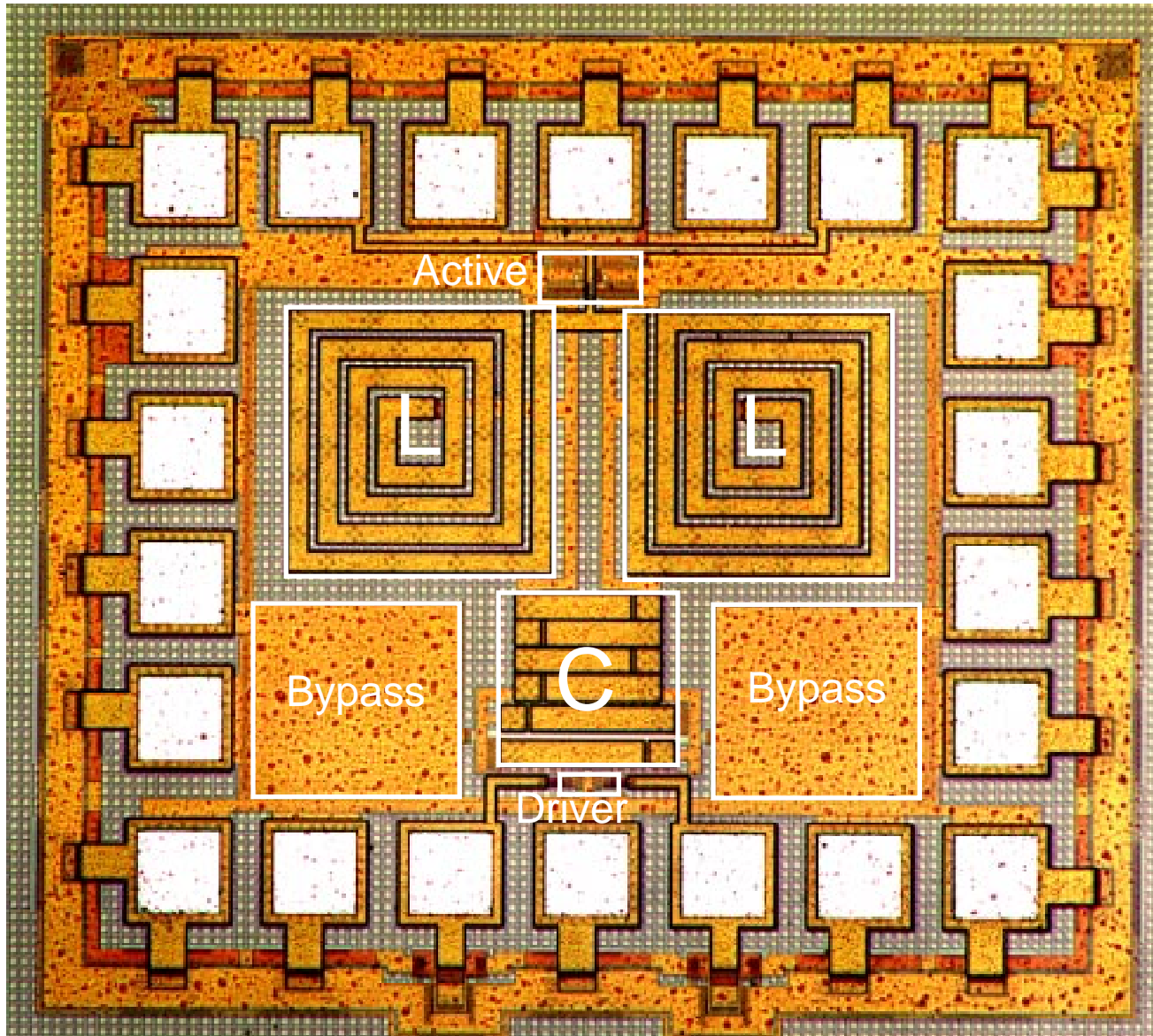
$f_0=1.8\text{GHz}$
 $P=6\text{mW}$
 -121dBc/Hz@600kHz

Complementary vs. NMOS-Only VCO

$f_0=1.8\text{GHz}$, $0.25\mu\text{m}$ Process



Die Photo of the Complementary Oscillator



0.25 μm Process

700 μm x 800 μm

Pad limited

Conclusion and Contributions

A new general model for phase noise is introduced, which:

- is independent of the topology of the oscillator,
- is useful both as an analysis and a design tool,
- is valid for arbitrary sources of noise and interference,
- predicts the effect of symmetry on the upconversion of $1/f$ noise,
- incorporates cyclostationary noise sources naturally,
- predicts the effect of correlation on phase noise,
- reduces to previously existing models as special cases,
- shows agreement among theory, simulation and measurements.

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